

7 Space

8 Space II



Mathematics  
and Statistics

$$\int_M d\omega = \int_{\partial M} \omega$$

# Mathematics 4MB3/6MB3 Mathematical Biology

Instructor: David Earn

Lecture 7

Space

Monday 28 October 2019

# Announcements

- **Midterm test:**

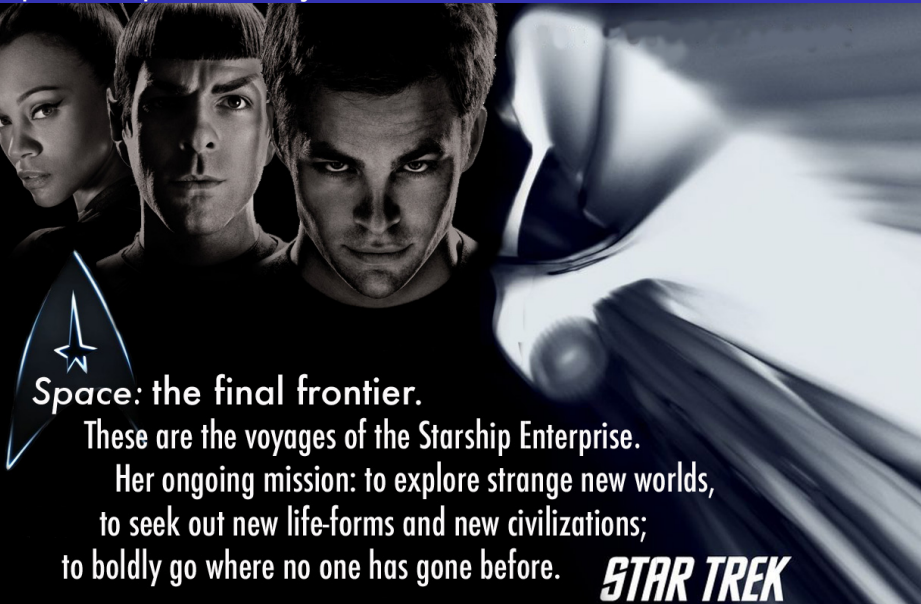
- *Date:* Monday 4 November 2019
- *Time:* 11:30am–1:30pm
- *Location:* in class, ETB-237

- **Assignment 4** is due the day of the midterm.

Due Monday 4 November 2019 before class.

- Make sure you personally can do the question on calculating  $\mathcal{R}_0$  on this assignment before the midterm test.

# Spatial Epidemic Dynamics



**Space: the final frontier.**

**These are the voyages of the Starship Enterprise.**

**Her ongoing mission: to explore strange new worlds,  
to seek out new life-forms and new civilizations;  
to boldly go where no one has gone before.**

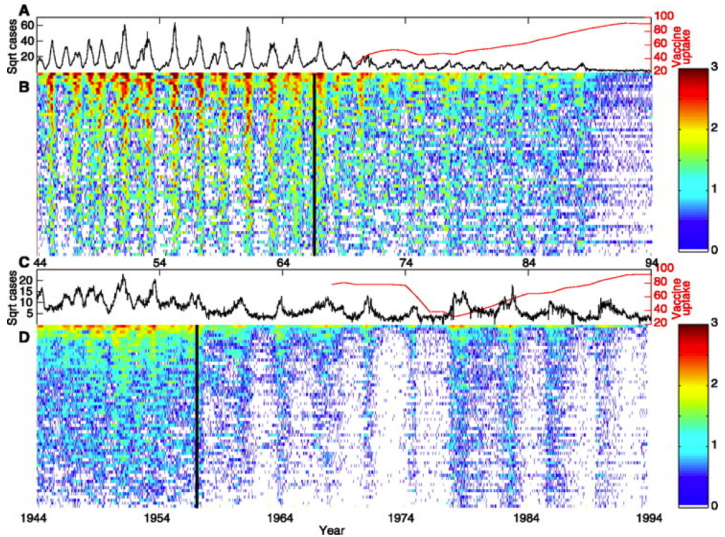
***STAR TREK***

# Something to think about

- All of our analysis has been of temporal patterns of epidemics
- What about spatial patterns?
- What problems are suggested by observed spatial epidemic patterns?
- Can spatial epidemic data suggest improved strategies for control?
- Can we reduce the eradication threshold below  $p_{\text{crit}} = 1 - \frac{1}{\mathcal{R}_0}$ ?

# Measles and Whooping Cough in 60 UK cities

Measles



Whooping  
Cough

Rohani, Earn & Grenfell (1999) *Science* 286, 968–971

# Better Control? Eradication?

- The term-time forced SEIR model successfully predicts past patterns of epidemics of childhood diseases
- Can we manipulate epidemics predictably so as to increase probability of eradication?
- Can we eradicate measles?

# Idea for eradicating measles

- Try to re-synchronize measles epidemics in the UK and, moreover, synchronize measles epidemics worldwide: synchrony is good
- Devise new vaccination strategy that tends to synchronize. . .
- Avoid spatially structured epidemics. . .
- Time to think about the mathematics of synchrony. . .
- But analytical theory of synchrony in a periodically forced system of differential equations is mathematically demanding. . .
- So let's consider a much simpler biological model. . .



# The Logistic Map

# Logistic Map

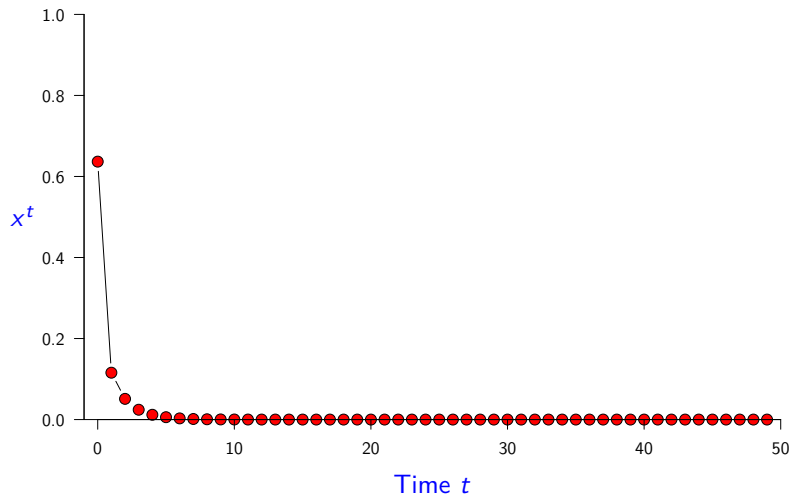
- Simplest non-trivial *discrete time* population model for a single species (with *non-overlapping generations*) in a *single habitat patch*.
- Time:  $t = 0, 1, 2, 3, \dots$
- State:  $x \in [0, 1]$  (population density)
- Population density at time  $t$  is  $x^t$ . Solutions are sequences:

$$x^0, x^1, x^2, \dots$$

- $x^{t+1} = F(x^t)$  for some *reproduction function*  $F(x)$ .
- For logistic map:  $F(x) = rx(1 - x)$ , so  $x^{t+1} = rx^t(1 - x^t)$ .  
 $x^{t+1} = [r(1 - x^t)]x^t \implies r$  is *maximum fecundity* (which is achieved in limit of very small population density).
- What kinds of dynamics are possible for the Logistic Map?

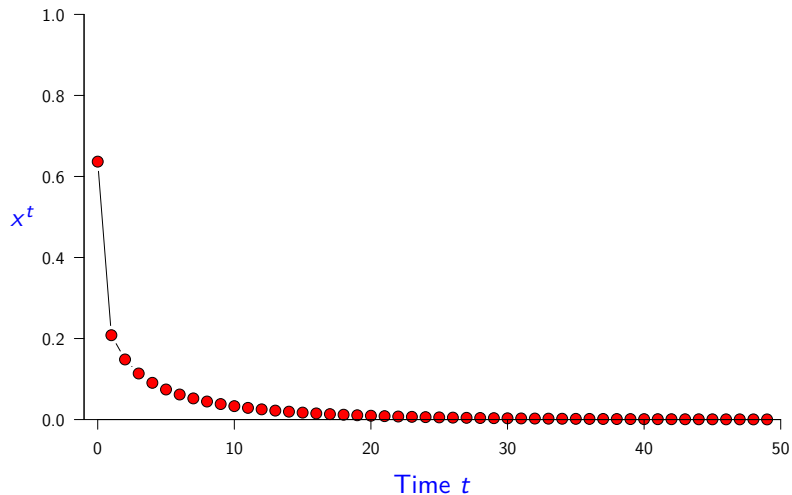
Logistic Map Time Series,  $r = 0.5$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 0.5, \quad x_0 = 0.63662$$



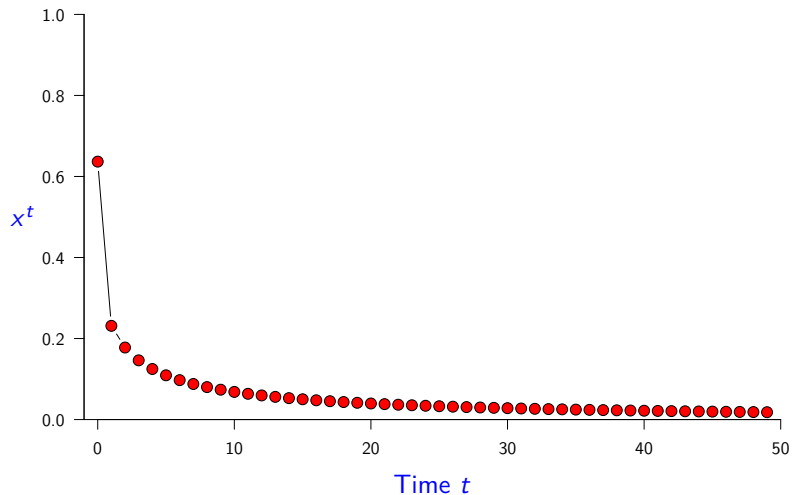
Logistic Map Time Series,  $r = 0.9$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 0.9, \quad x_0 = 0.63662$$



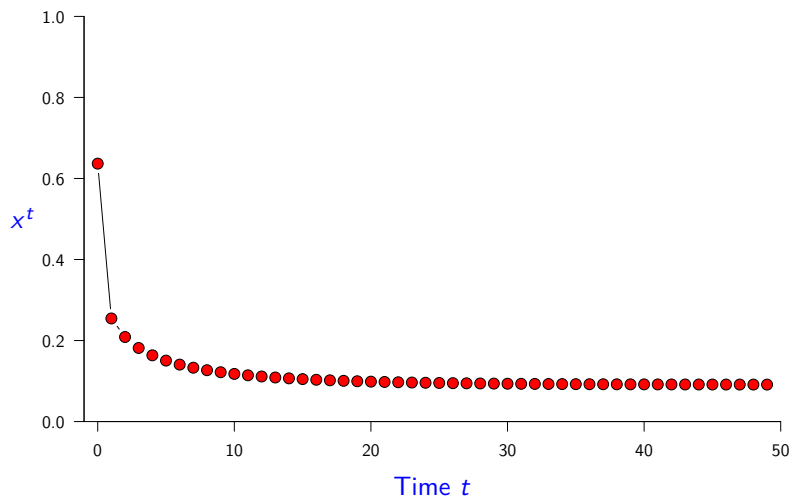
Logistic Map Time Series,  $r = 1$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 1, \quad x_0 = 0.63662$$



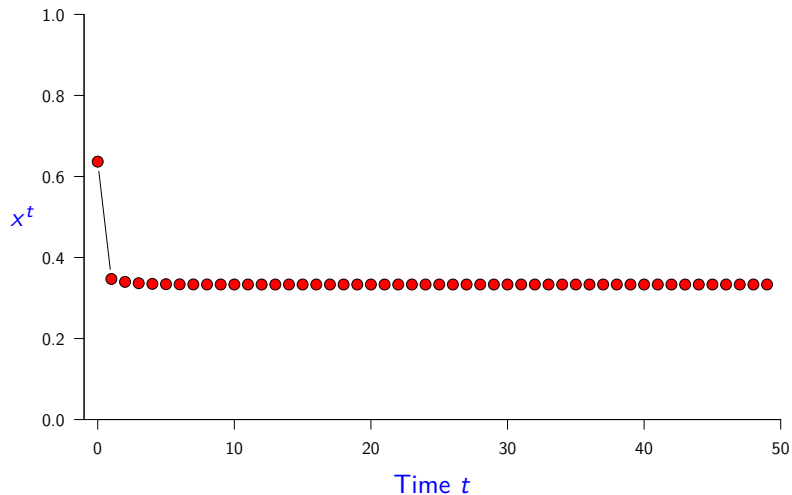
Logistic Map Time Series,  $r = 1.1$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 1.1, \quad x_0 = 0.63662$$



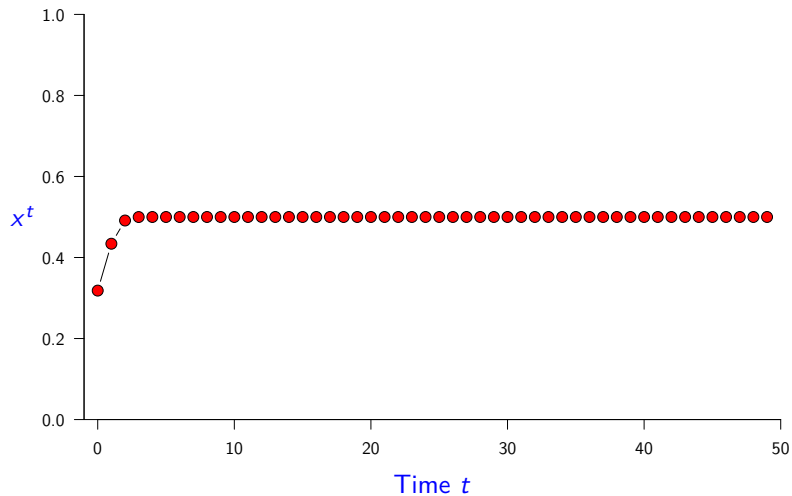
Logistic Map Time Series,  $r = 1.5$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 1.5, \quad x_0 = 0.63662$$



Logistic Map Time Series,  $r = 2$ 

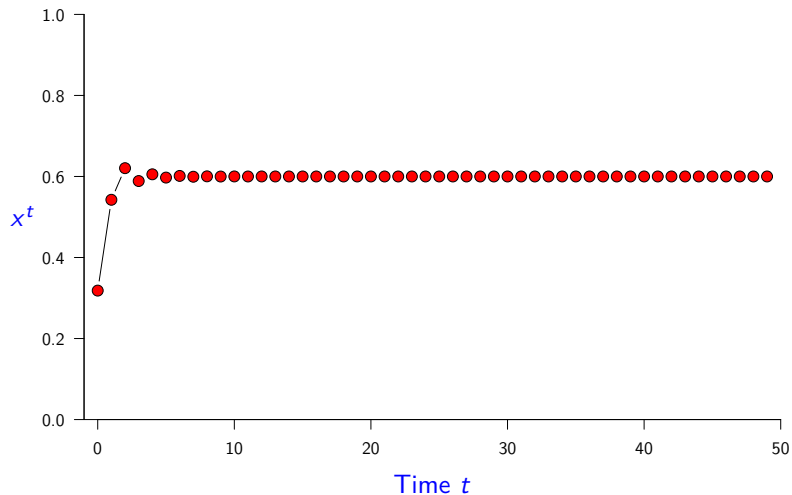
$$x^{t+1} = rx^t(1 - x^t), \quad r = 2, \quad x_0 = 0.31831$$





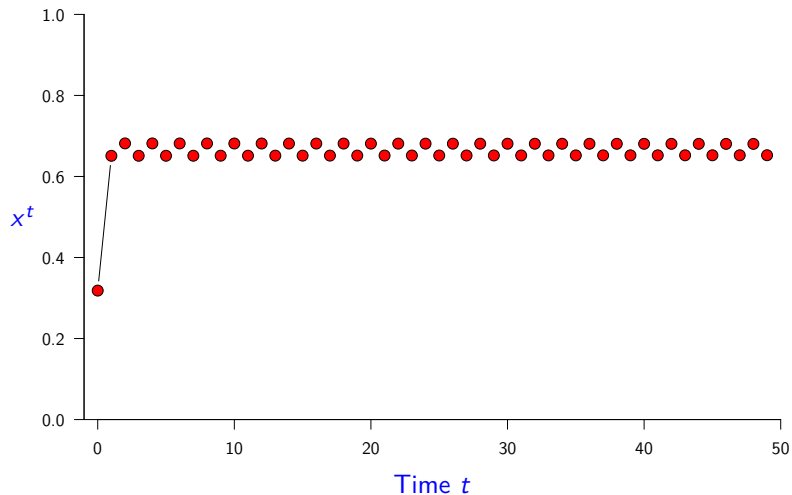
Logistic Map Time Series,  $r = 2.5$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 2.5, \quad x_0 = 0.31831$$



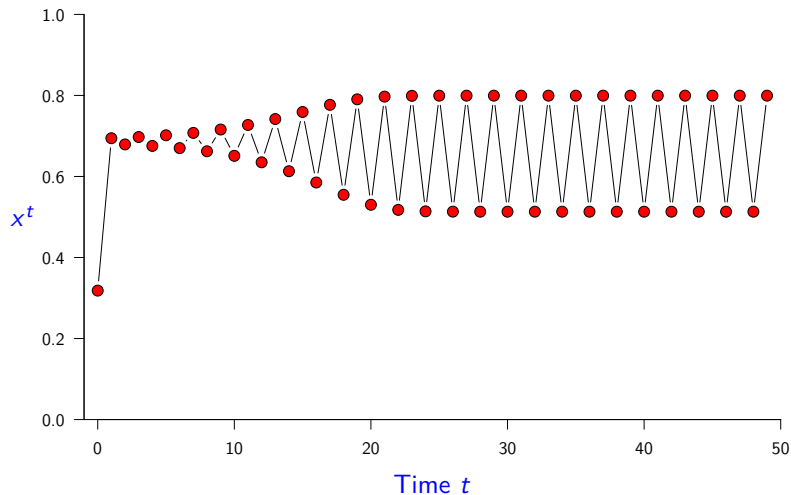
Logistic Map Time Series,  $r = 3$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 3, \quad x_0 = 0.31831$$



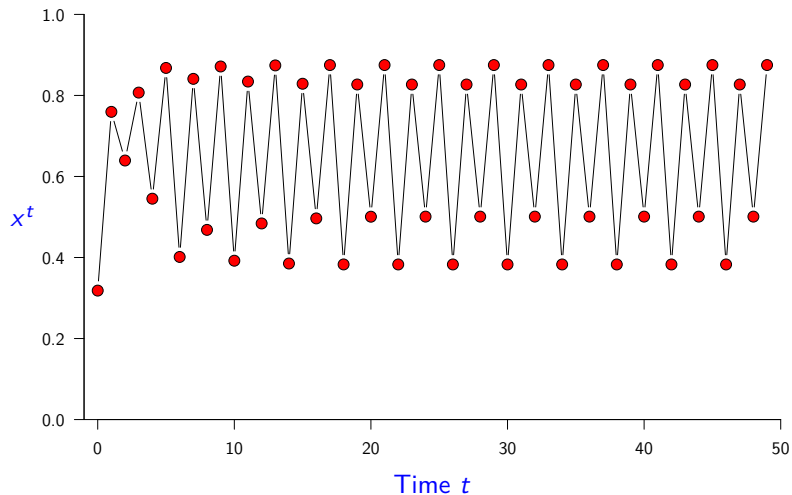
Logistic Map Time Series,  $r = 3.2$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 3.2, \quad x_0 = 0.31831$$



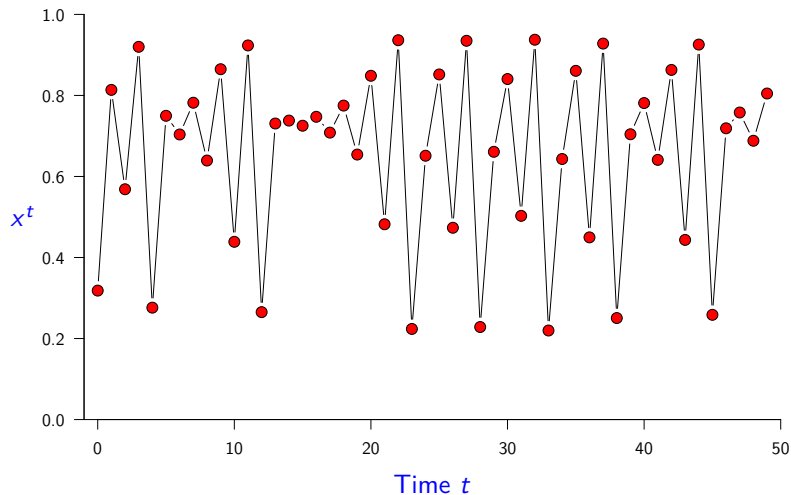
Logistic Map Time Series,  $r = 3.5$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 3.5, \quad x_0 = 0.31831$$



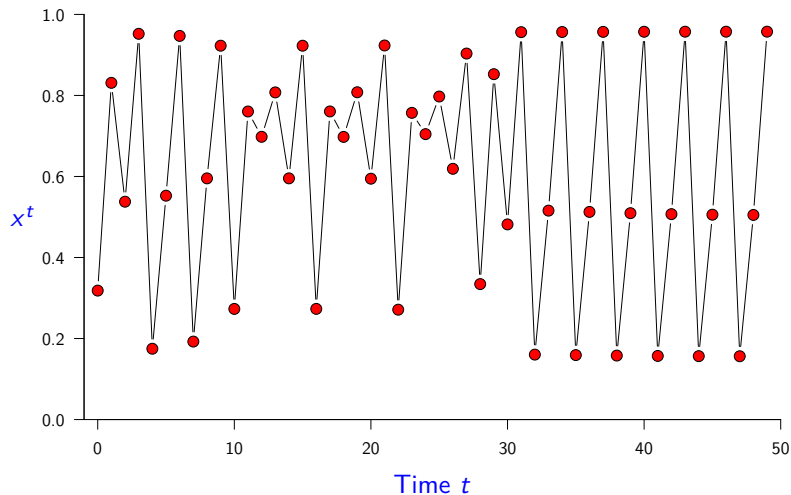
Logistic Map Time Series,  $r = 3.75$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 3.75, \quad x_0 = 0.31831$$



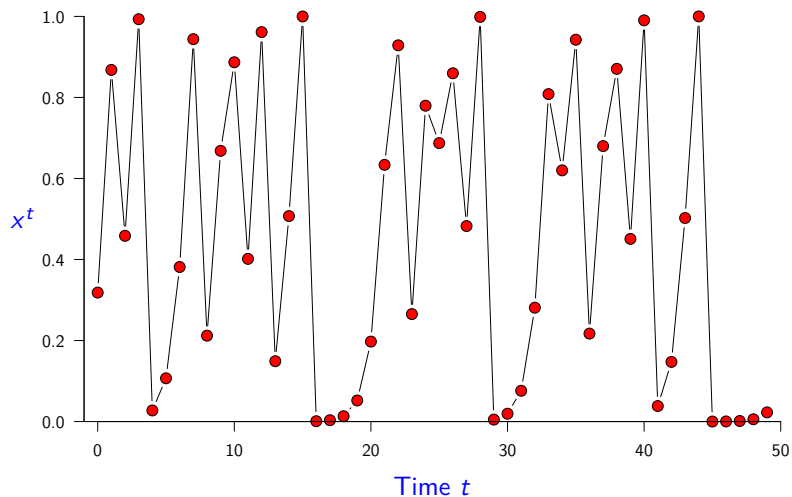
Logistic Map Time Series,  $r = 3.83$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 3.83, \quad x_0 = 0.31831$$



Logistic Map Time Series,  $r = 4$ 

$$x^{t+1} = rx^t(1 - x^t), \quad r = 4, \quad x_0 = 0.31831$$

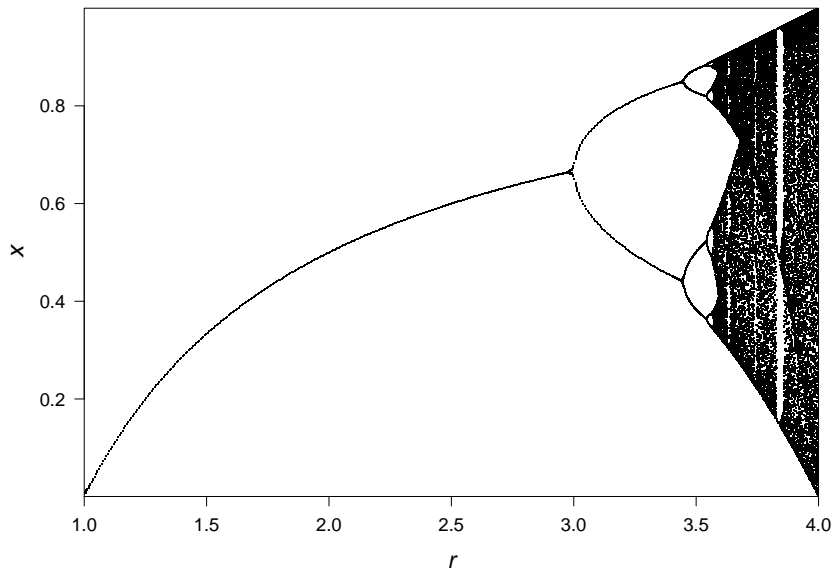


# Logistic Map Summary

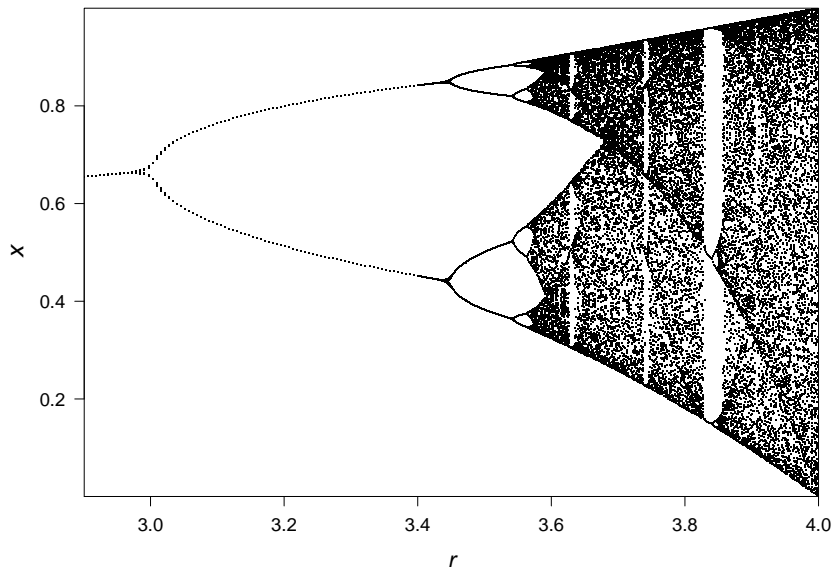
- Time series show:
  - $r \leq 1 \implies$  Extinction.
  - $1 < r < 3 \implies$  Persistence at equilibrium.
  - $r > 3 \implies$  period doubling cascade to chaos, then appearance of cycles of all possible lengths, and more chaos, . . .
- How can we summarize this in a diagram?
  - Bifurcation diagram (wrt  $r$ ).
  - Ignore transient behaviour: just show attractor.



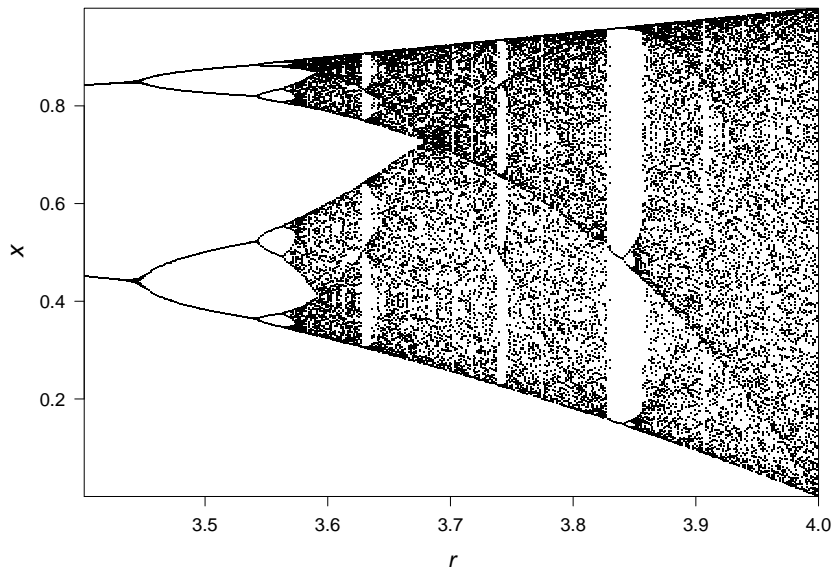
Logistic Map,  $F(x) = rx(1 - x)$ ,  $1 \leq r \leq 4$



Logistic Map,  $F(x) = rx(1 - x)$ ,  $2.9 \leq r \leq 4$



Logistic Map,  $F(x) = rx(1 - x)$ ,  $3.4 \leq r \leq 4$



# Logistic Map as a Tool to Investigate Synchrony

- Very simple single-patch model: only one state variable.
- Displays **all kinds of dynamics** from GAS equilibrium, to periodic orbits, to chaos.
  - This was *extremely surprising* to population biologists and mathematicians in the 1970s.

May RM (1976) "Simple mathematical models with very complicated dynamics" *Nature* **261**, 459–467

- Easier to work with logistic map as single patch dynamics than SIR or SEIR model.
- Can still understand how synchrony works conceptually.
- Now we are ready for the ...

... *Mathematics of Synchrony* ...

# Mathematics of Synchrony

- System comprised of isolated *patches*  
e.g., cities, labelled  $i = 1, \dots, n$
- *State* of system in patch  $i$  specified by  $\mathbf{x}_i$   
e.g.,  $\mathbf{x}_i = (S_i, E_i, I_i, R_i)$
- Connectivity of patches specified by a *dispersal matrix*  
 $M = (m_{ij})$
- System is *coherent* (perfectly synchronous) if the state is the same in all patches  
i.e.,  $\mathbf{x}_1 = \mathbf{x}_2 = \dots = \mathbf{x}_n$

# Illustrative example: logistic metapopulation

- *Single patch model:*  $x^{t+1} = F(x^t)$
- *Reproduction function:*  $F(x) = rx(1 - x)$
- *Multi-patch model:*  $x_i^{t+1} = \sum_{j=1}^n m_{ij} F(x_j^t)$

$$i.e., \begin{pmatrix} x_1^{t+1} \\ \vdots \\ x_n^{t+1} \end{pmatrix} = \begin{pmatrix} m_{11} & \cdots & m_{1n} \\ \vdots & \ddots & \vdots \\ m_{n1} & \cdots & m_{nn} \end{pmatrix} \begin{pmatrix} F(x_1^t) \\ \vdots \\ F(x_n^t) \end{pmatrix}$$

where  $M = (m_{ij})$  is *dispersal matrix*.

- *Colour coding of indices:*
  - row indices are red
  - column indices are cyan

# Basic properties of dispersal matrices $M = (m_{ij})$

Discrete-time *metapopulation* model:

$$x_i^{t+1} = \sum_{j=1}^n m_{ij} F(x_j^t), \quad i = 1, 2, \dots, n.$$

- $m_{ij}$  = *proportion* of population in patch  $j$  that disperses to patch  $i$ .
- $\therefore 0 \leq m_{ij} \leq 1$  for all  $i$  and  $j$   
(each  $m_{ij}$  is non-negative and at most 1)
- Total proportion that leaves or stays in patch  $j$ :  $\sum_{i=1}^n m_{ij}$   
(sum of column  $j$ )
- $\therefore \sum_{i=1}^n m_{ij} \leq 1$  (every column sums to at most 1)

Could be  $< 1$  if some individuals are lost (die) while dispersing.

# Basic properties of dispersal matrices $M = (m_{ij})$

Discrete-time *metapopulation* model:

$$x_i^{t+1} = \sum_{j=1}^n m_{ij} F(x_j^t), \quad i = 1, 2, \dots, n.$$

## Definition (No loss dispersal matrix)

An  $n \times n$  matrix  $M = (m_{ij})$  is said to be a **no loss dispersal matrix** if all its entries are non-negative ( $m_{ij} \geq 0$  for all  $i$  and  $j$ ) and its column sums are all 1, *i.e.*,

$$\sum_{i=1}^n m_{ij} = 1, \quad \text{for each } j = 1, \dots, n.$$

- The dispersal process is “conservative” in this case.
- A no loss dispersal matrix is also said to be “column stochastic”.



# Notation for coherent states

Discrete-time *metapopulation* model:

$$x_i^{t+1} = \sum_{j=1}^n m_{ij} F(x_j^t), \quad i = 1, 2, \dots, n.$$

- State at time  $t$  is  $\mathbf{x}^t = (x_1^t, \dots, x_n^t) \in \mathbb{R}^n$ .
- If state  $\mathbf{x}$  is *coherent*, then for some  $x \in \mathbb{R}$  we have

$$\begin{aligned} \mathbf{x} &= (x_1, x_2, \dots, x_n) \\ &= (x, x, \dots, x) = x(1, 1, \dots, 1) \end{aligned}$$

- For convenience, define

$$\mathbf{e} = (1, 1, \dots, 1) \in \mathbb{R}^n$$

*so any coherent state can be written  $x\mathbf{e}$ , for some  $x \in \mathbb{R}$ .*

# Constraint on row sums of dispersal matrix $M$

Lemma (Row sums are the same)

*If all initially coherent states remain coherent then the row sums of the dispersal matrix are all the same.*

Proof.

Suppose initially coherent states remain coherent, i.e.,

$\mathbf{x}^t = a\mathbf{e} \implies \mathbf{x}^{t+1} = b\mathbf{e}$  for some  $b \in \mathbb{R}$ .

Choose  $a$  such that  $F(a) \neq 0$ . Then

$$\begin{aligned}x_i^{t+1} = b &= \sum_{j=1}^n m_{ij} F(x_j^t) = \sum_{j=1}^n m_{ij} F(a) = F(a) \sum_{j=1}^n m_{ij} \\ \implies \sum_{j=1}^n m_{ij} &= \frac{b}{F(a)} \quad (\text{independent of } i)\end{aligned}$$



# Constraint on row sums of dispersal matrix $M$

## Lemma (Row sums are all 1)

*If every solution  $\{x^t\}$  of the single patch map  $F(x)$  yields a coherent solution  $\{x^t e\}$  of the full map then the row sums of the dispersal matrix are all 1.*

## Proof.

Suppose  $x^t = a e \implies x^{t+1} = F(a)e$  and  $F(a) \neq 0$ . Then

$$\begin{aligned}x_i^{t+1} &= F(a) = \sum_{j=1}^n m_{ij} F(x_j^t) = \sum_{j=1}^n m_{ij} F(a) = F(a) \sum_{j=1}^n m_{ij} \\ &\implies \sum_{j=1}^n m_{ij} = 1 \quad (\text{independent of } i)\end{aligned}$$



# Project

You should be thinking about your **Project**...

- Remember your group must give an oral presentation of your project as well (in the last class).
- Classes after the midterm are NOT optional. Your group is expected to meet in class and take advantage of the instructor's presence to solve issues with your project.
- Project Notebook template is posted on [project](#) page.
- Movie night?

# Midterm Test

Student Name: \_\_\_\_\_

Student Number: \_\_\_\_\_

**MATHEMATICS 4MB3/6MB3**  
**Midterm Test, Monday 11 March 2019**

## Special Instructions and Notes:

- (i) This test has **12** pages. Verify that your copy is complete. Note that the final two pages are blank to provide additional space if needed.
- (ii) Clearly write your name and student number at the top of each page.
- (iii) **Answer all questions in the space provided.**
- (iv) It is possible to obtain a total of 50 marks. There are 10 multiple choice questions (2 marks each) and 10 short answer questions (total of 30 marks).
- (v) **For multiple choice questions, circle only one answer.**
- (vi) No calculators, notes, or aids of any kind are permitted.
- (vii) PHAC refers to the Public Health Agency of Canada.

**GOOD LUCK**

# Midterm Test

- The test will cover everything from lectures and assignments/solutions up to and including today.
- Material connected with time series analysis and synchrony/coherence will occur only in multiple choice questions.
- You are assumed to be comfortable with:
  - Elementary algebra, including finding the eigenvalues of  $2 \times 2$  matrices.
  - Stability analyses of differential equations.
  - Finding  $\mathcal{R}_0$  by biological and mathematical [ $\rho(FV^{-1})$ ] methods.
  - Converting flow charts or verbal descriptions into compartmental ODE models.
- You will be presented with scenarios including graphs, and asked to write explanations that would be understandable by people at PHAC.

# Let's review what we've done so far on spatial models. . .

- Logistic metapopulation model
- Notion of coherence
- No-loss dispersal matrix  $M$ : column sums are all 1
- To retain homogeneous solutions: row sums are all 1

## Simple examples of no loss dispersal matrices

- *Equal coupling*: a proportion  $m$  from each patch disperses uniformly among the other  $n - 1$  patches:

$$m_{ij} = \begin{cases} 1 - m & i = j \\ m/(n - 1) & i \neq j \end{cases}$$

- *Nearest-neighbour coupling*: a proportion  $m$  go to the two nearest patches:

$$m_{ij} = \begin{cases} 1 - m & i = j \\ m/2 & i = j - 1 \text{ or } j + 1 \pmod{n} \\ 0 & \text{otherwise} \end{cases}$$

- Real dispersal patterns generally between these two extremes

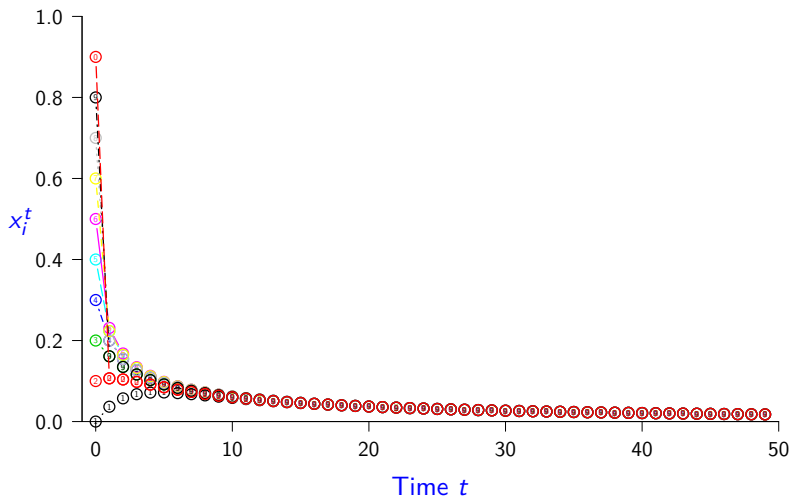


# Key Question

- Can we find conditions on the dispersal matrix  $M$ , and/or the single patch reproduction function  $F$ , that guarantee (or preclude) coherence asymptotically (as  $t \rightarrow \infty$ )?
  - If so, then this sort of analysis should help to identify synchronizing vaccination strategies.

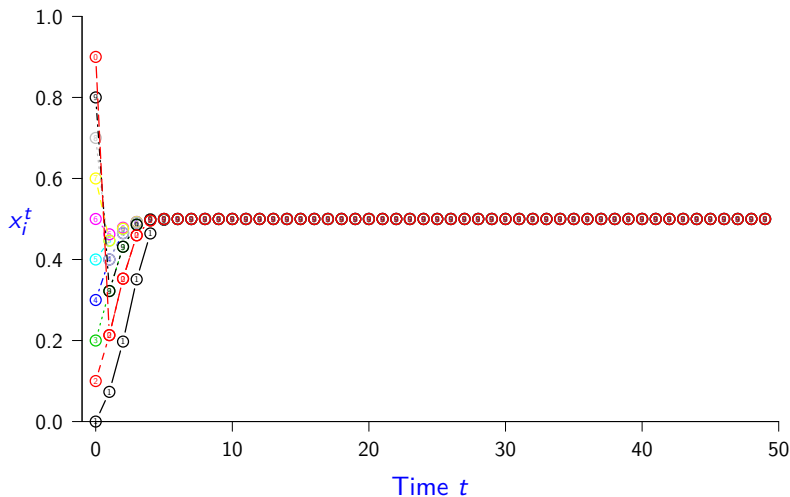
Logistic Metapopulation Simulation ( $r = 1, m = 0.2$ )

$$n = 10, \quad r = 1, \quad m = 0.2, \quad \lambda = 0.778$$



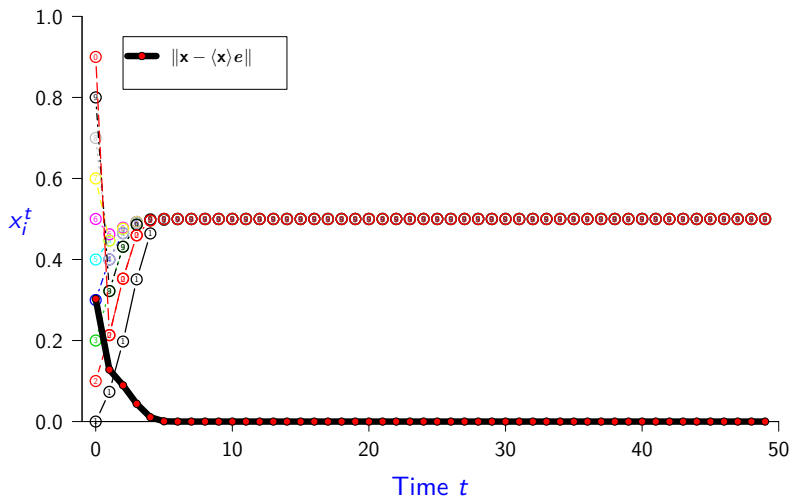
Logistic Metapopulation Simulation ( $r = 2$ ,  $m = 0.2$ )

$$n = 10, \quad r = 2, \quad m = 0.2, \quad \lambda = 0.778$$



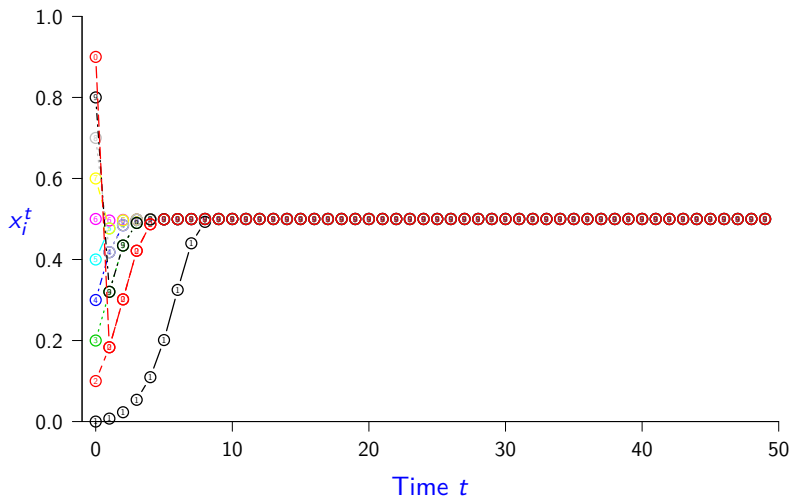
# Logistic Metapopulation Simulation ( $r = 2, m = 0.2$ )

$$n = 10, \quad r = 2, \quad m = 0.2, \quad \lambda = 0.778$$



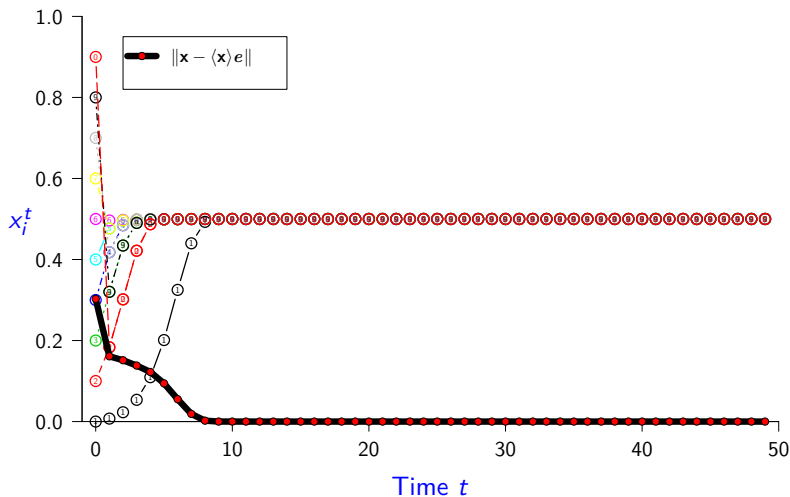
Logistic Metapopulation Simulation ( $r = 2$ ,  $m = 0.02$ )

$$n = 10, \quad r = 2, \quad m = 0.02, \quad \lambda = 0.978$$



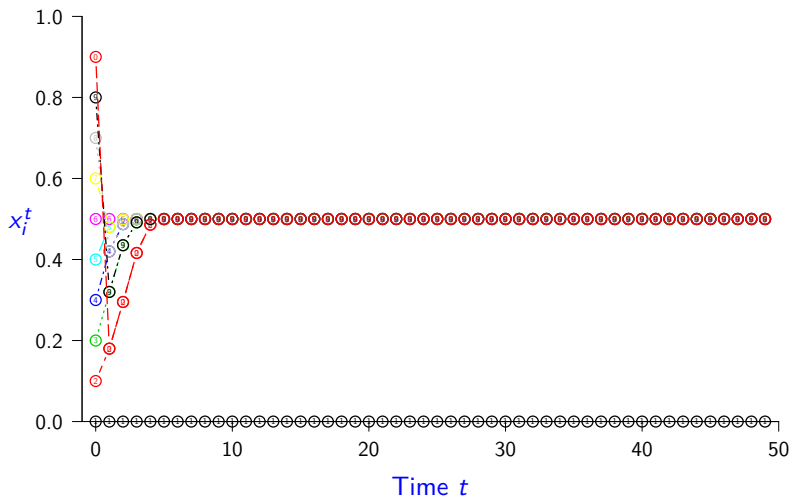
# Logistic Metapopulation Simulation ( $r = 2, m = 0.02$ )

$$n = 10, \quad r = 2, \quad m = 0.02, \quad \lambda = 0.978$$



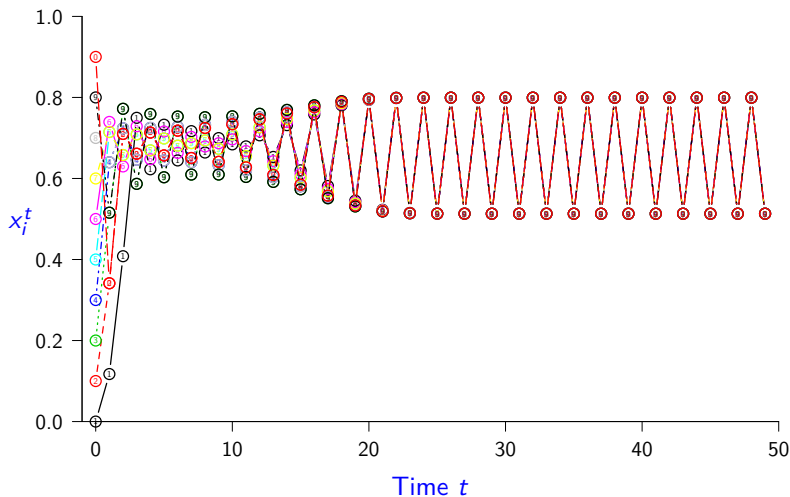
# Logistic Metapopulation Simulation ( $r = 2, m = 0$ )

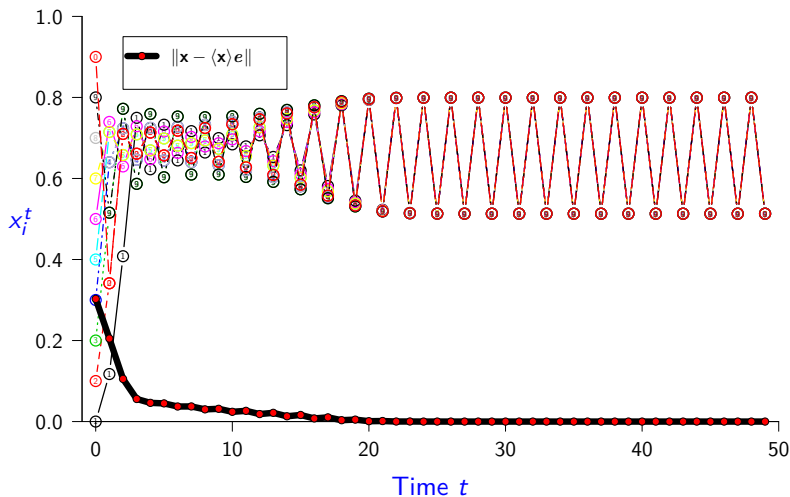
$$n = 10, \quad r = 2, \quad m = 0, \quad \lambda = 1$$

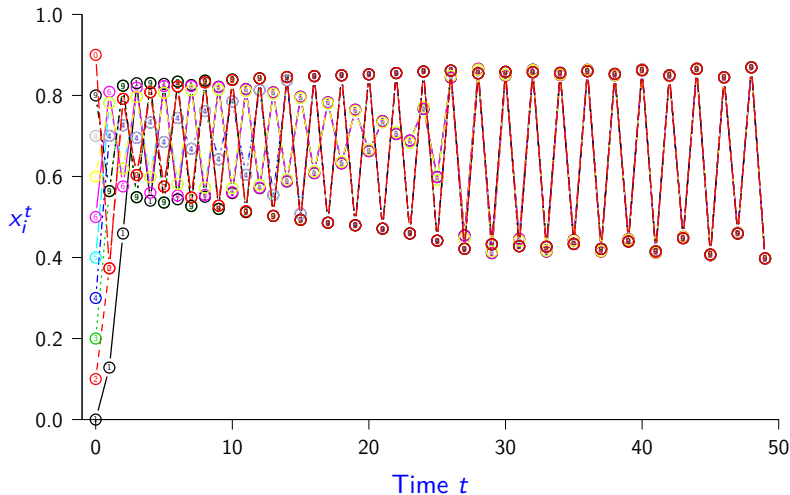






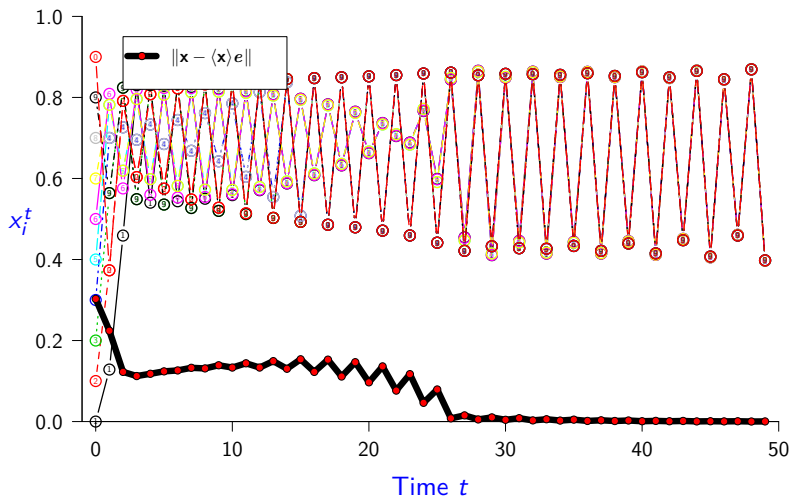
Logistic Metapopulation Simulation ( $r = 3.2$ ,  $m = 0.2$ ) $n = 10$ ,  $r = 3.2$ ,  $m = 0.2$ ,  $\lambda = 0.778$ 

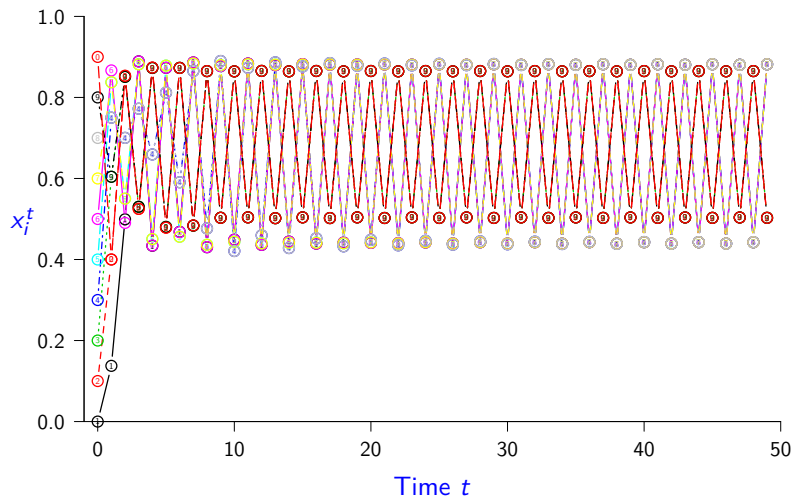
Logistic Metapopulation Simulation ( $r = 3.2, m = 0.2$ ) $n = 10, \quad r = 3.2, \quad m = 0.2, \quad \lambda = 0.778$ 

Logistic Metapopulation Simulation ( $r = 3.5$ ,  $m = 0.2$ ) $n = 10$ ,  $r = 3.5$ ,  $m = 0.2$ ,  $\lambda = 0.778$ 

# Logistic Metapopulation Simulation ( $r = 3.5, m = 0.2$ )

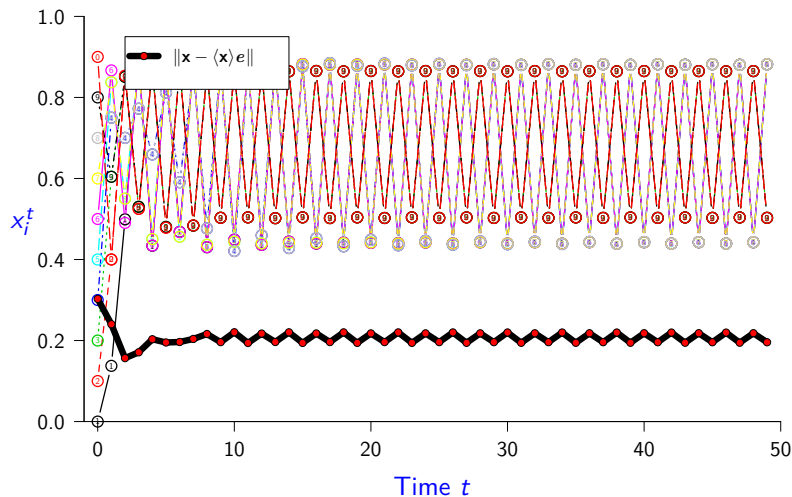
$n = 10, \quad r = 3.5, \quad m = 0.2, \quad \lambda = 0.778$

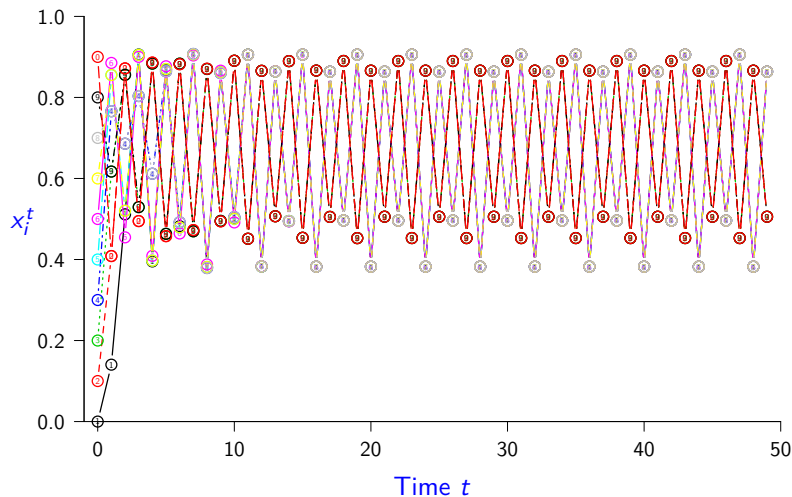


Logistic Metapopulation Simulation ( $r = 3.75$ ,  $m = 0.2$ ) $n = 10$ ,  $r = 3.75$ ,  $m = 0.2$ ,  $\lambda = 0.778$ 

# Logistic Metapopulation Simulation ( $r = 3.75$ , $m = 0.2$ )

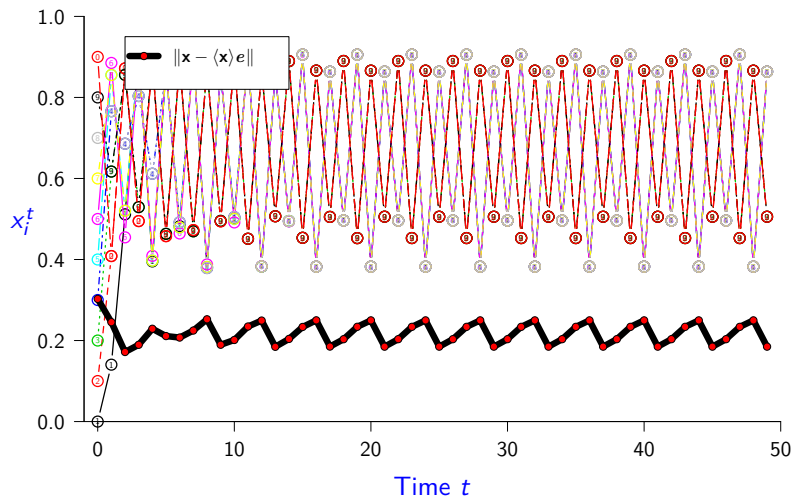
$$n = 10, \quad r = 3.75, \quad m = 0.2, \quad \lambda = 0.778$$



Logistic Metapopulation Simulation ( $r = 3.83$ ,  $m = 0.2$ ) $n = 10$ ,  $r = 3.83$ ,  $m = 0.2$ ,  $\lambda = 0.778$ 

# Logistic Metapopulation Simulation ( $r = 3.83$ , $m = 0.2$ )

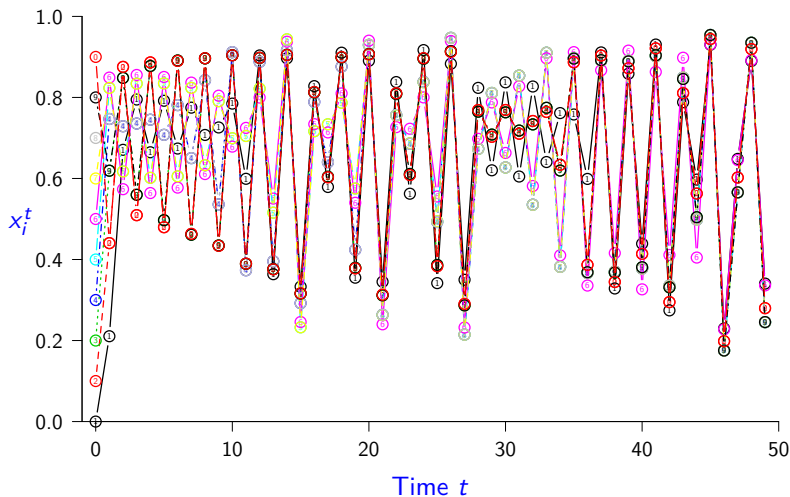
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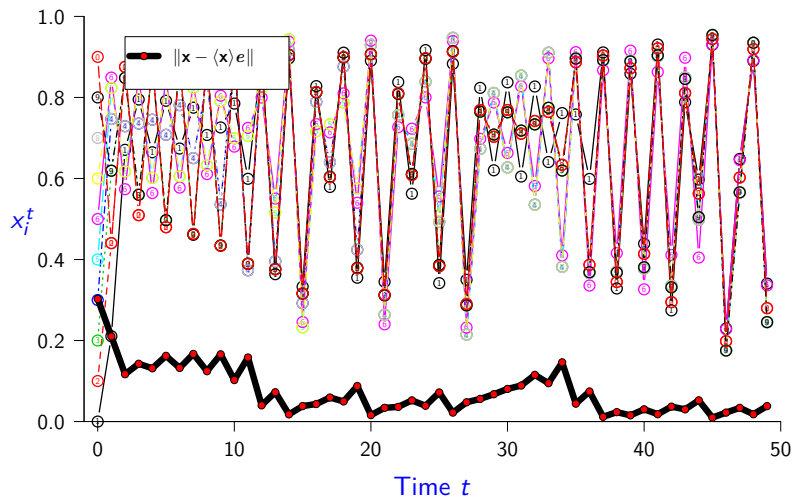


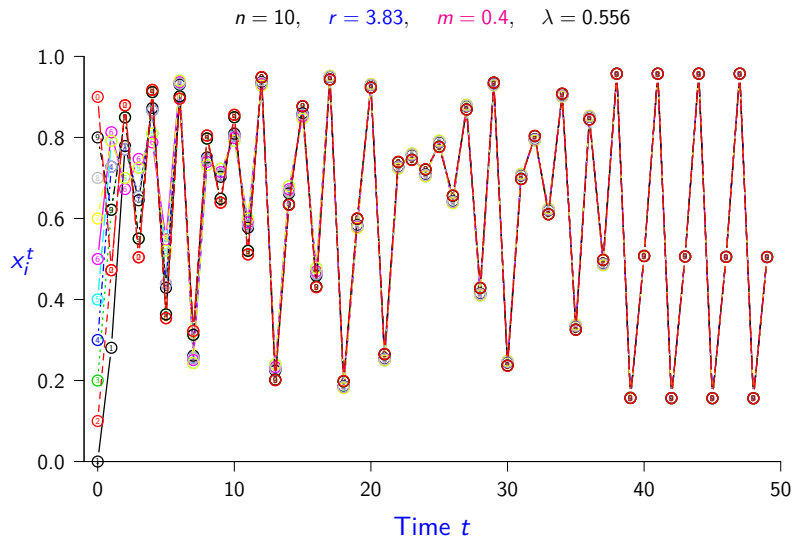


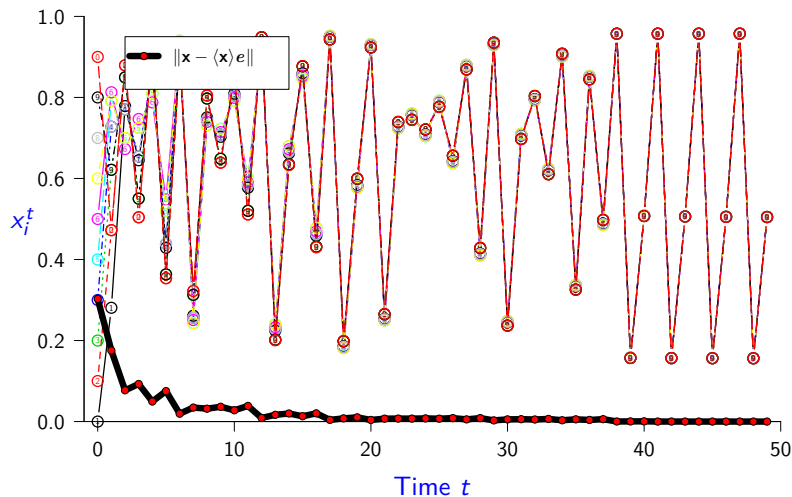
# Logistic Metapopulation Simulation ( $r = 3.83$ , $m = 0.3$ )

$n = 10$ ,  $r = 3.83$ ,  $m = 0.3$ ,  $\lambda = 0.667$



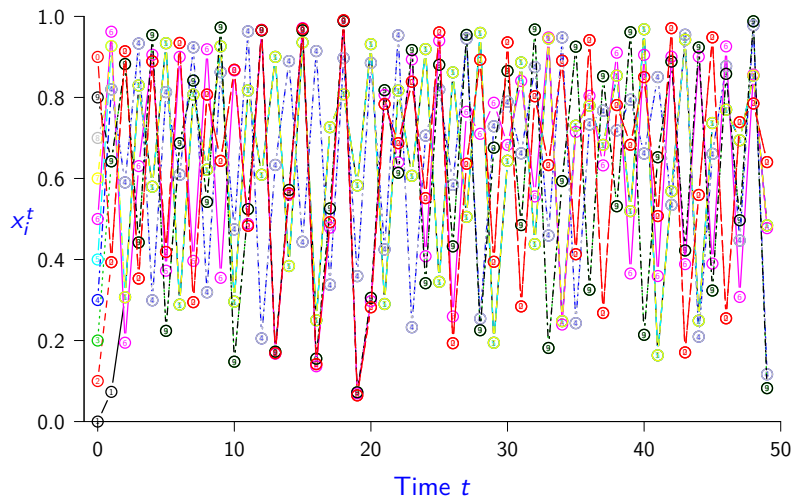
Logistic Metapopulation Simulation ( $r = 3.83$ ,  $m = 0.3$ ) $n = 10$ ,  $r = 3.83$ ,  $m = 0.3$ ,  $\lambda = 0.667$ 

Logistic Metapopulation Simulation ( $r = 3.83$ ,  $m = 0.4$ )

Logistic Metapopulation Simulation ( $r = 3.83$ ,  $m = 0.4$ ) $n = 10$ ,  $r = 3.83$ ,  $m = 0.4$ ,  $\lambda = 0.556$ 

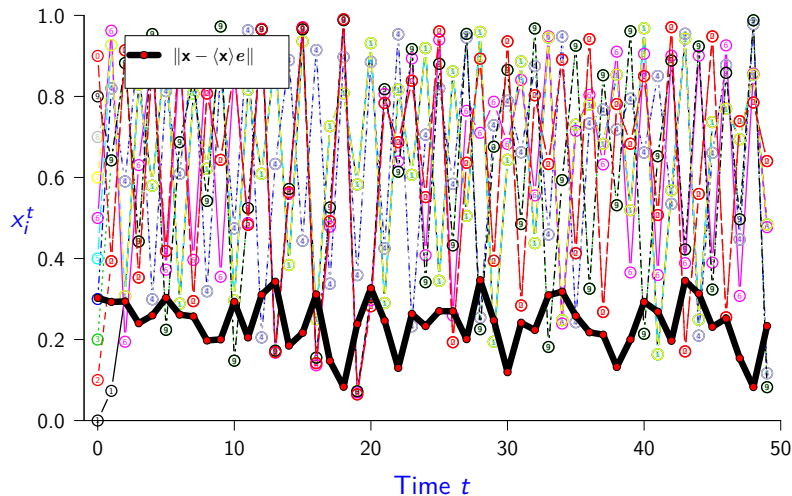
# Logistic Metapopulation Simulation ( $r = 4, m = 0.1$ )

$n = 10, r = 4, m = 0.1, \lambda = 0.889$



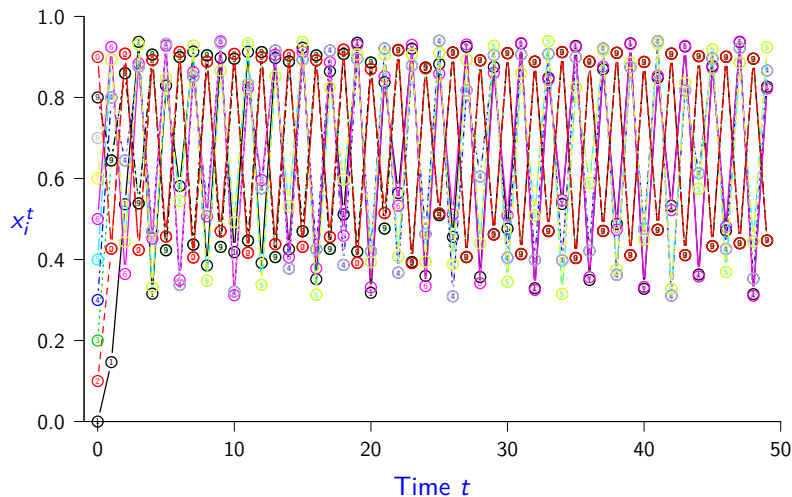
# Logistic Metapopulation Simulation ( $r = 4, m = 0.1$ )

$n = 10, r = 4, m = 0.1, \lambda = 0.889$



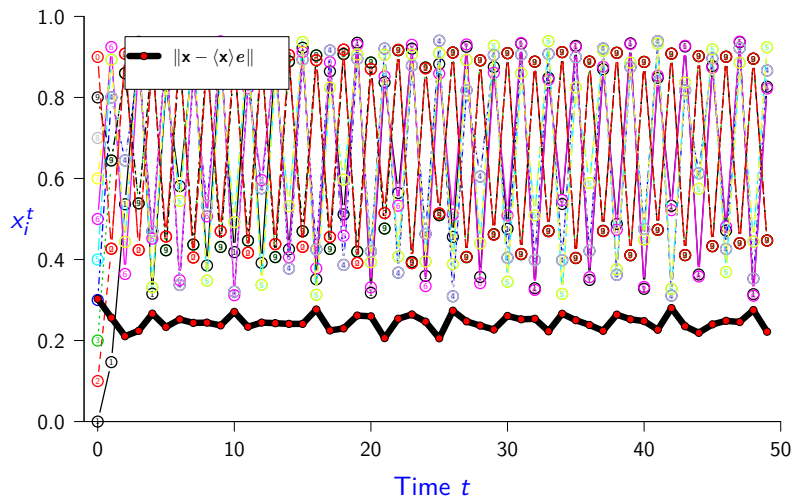
# Logistic Metapopulation Simulation ( $r = 4, m = 0.2$ )

$n = 10, r = 4, m = 0.2, \lambda = 0.778$

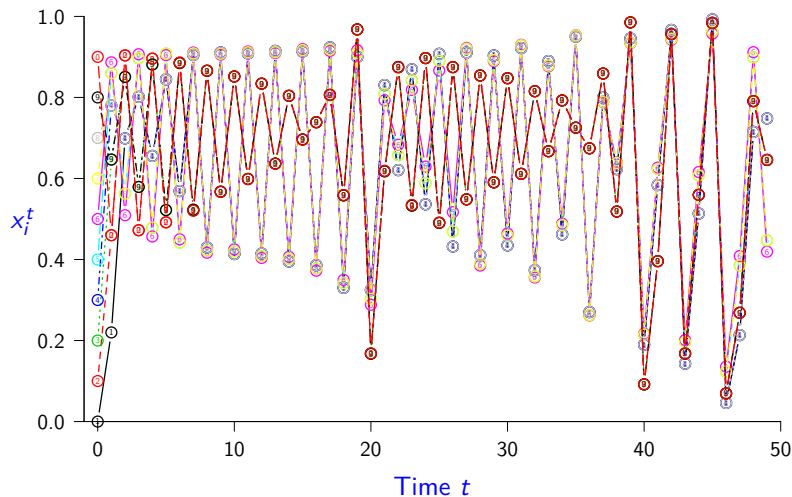


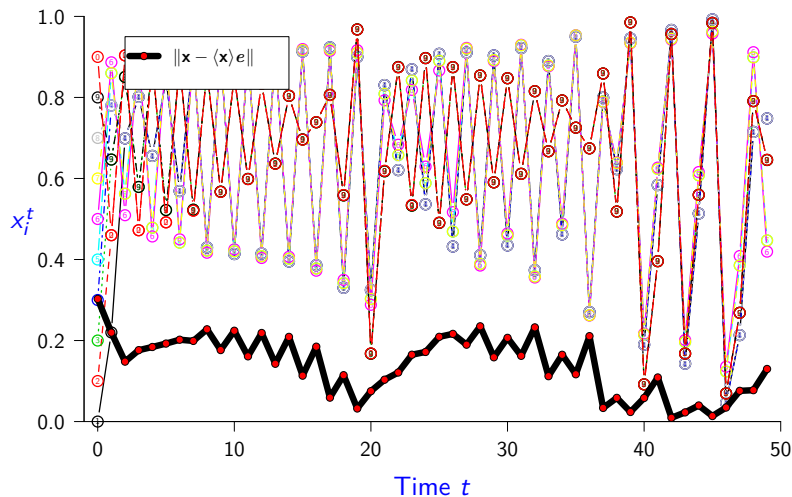
# Logistic Metapopulation Simulation ( $r = 4, m = 0.2$ )

$n = 10, r = 4, m = 0.2, \lambda = 0.778$



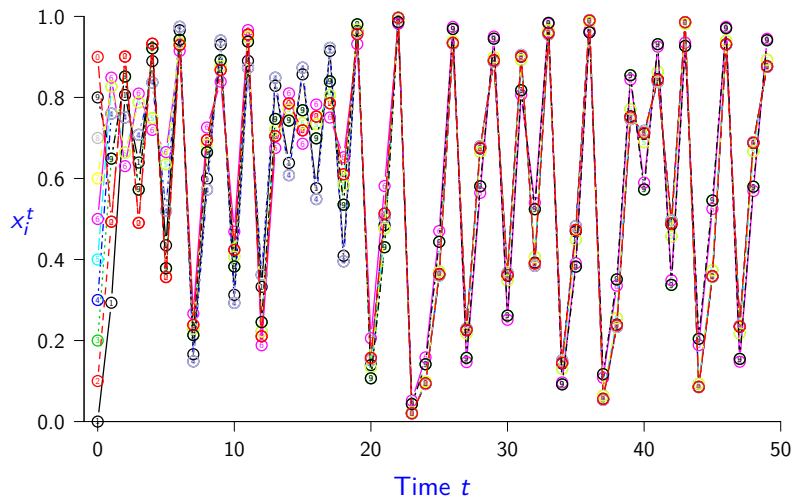


Logistic Metapopulation Simulation ( $r = 4, m = 0.3$ ) $n = 10, r = 4, m = 0.3, \lambda = 0.667$ 

Logistic Metapopulation Simulation ( $r = 4, m = 0.3$ ) $n = 10, r = 4, m = 0.3, \lambda = 0.667$ 

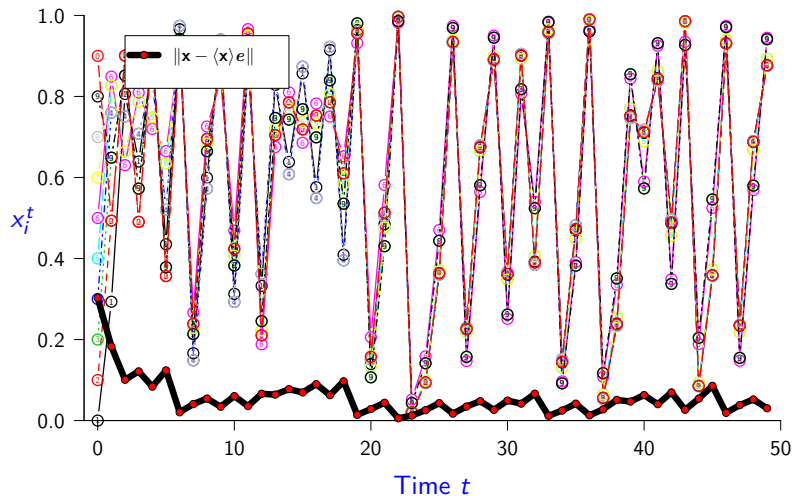
# Logistic Metapopulation Simulation ( $r = 4, m = 0.4$ )

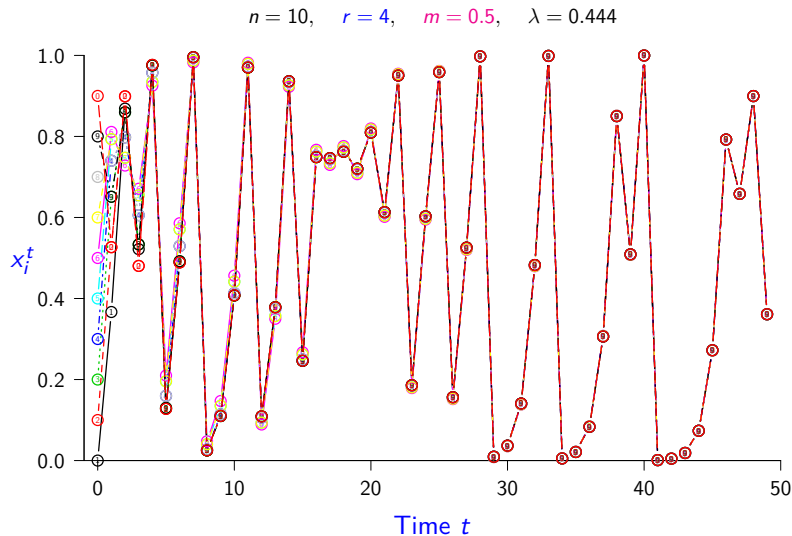
$n = 10, r = 4, m = 0.4, \lambda = 0.556$



# Logistic Metapopulation Simulation ( $r = 4, m = 0.4$ )

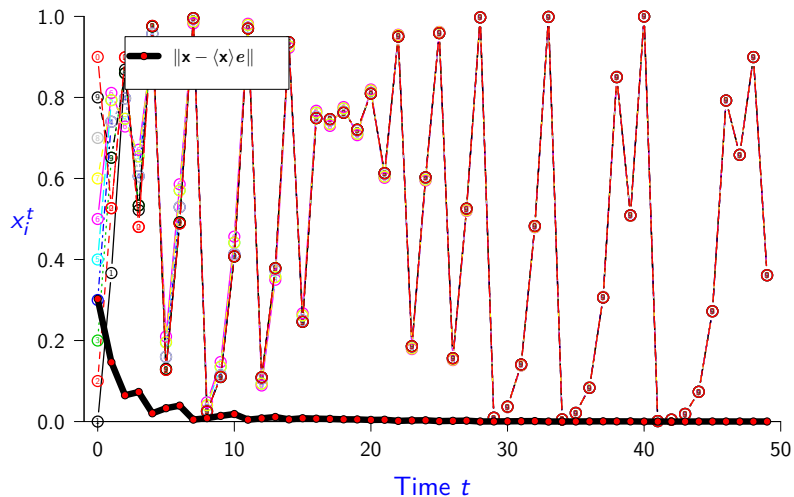
$n = 10, r = 4, m = 0.4, \lambda = 0.556$



Logistic Metapopulation Simulation ( $r = 4, m = 0.5$ )

# Logistic Metapopulation Simulation ( $r = 4, m = 0.5$ )

$n = 10, \quad r = 4, \quad m = 0.5, \quad \lambda = 0.444$



# Metapopulation dynamics: what we've seen so far

- Examples of connectivity matrices

- equal coupling

- nearest-neighbour coupling on a ring

- Logistic Metapopulation Simulations (10 patches)

- $r = 1, m = 0.2$

- $r = 3.5, m = 0.2$

- $r = 4, m = 0.1$

- $r = 2, m = 0.2$

- $r = 3.75, m = 0.2$

- $r = 4, m = 0.2$

- $r = 2, m = 0.02$

- $r = 3.83, m = 0.2$

- $r = 4, m = 0.3$

- $r = 2, m = 0$

- $r = 3.83, m = 0.3$

- $r = 4, m = 0.4$

- $r = 3.2, m = 0.2$

- $r = 3.83, m = 0.4$

- $r = 4, m = 0.5$

# Quantities that affect coherence

## *Degree of spatial coupling:*

- Determined by dispersal matrix  $M = (m_{ij})$ .
- Do we need to worry about about all matrix entries?  
 $n^2$  parameters?
- Are eigenvalues enough?
- Dominant eigenvalue is always 1. Why?
  - Next slide. . .
- Coherence is affected by magnitude  $|\lambda|$  of *subdominant eigenvalue*  $\lambda$ .



# Dominant eigenvalue of dispersal matrix $M$ is always 1

## Definition (Positive vector)

A vector is **positive** if each of its components is positive.

## Definition (Dominant eigenvalue)

$\lambda$  is a **dominant eigenvalue** of a matrix  $A$  if no other eigenvalue of  $A$  has larger magnitude.

## Theorem

*Let  $A$  be a nonnegative matrix. If  $A$  has a positive eigenvector then the corresponding eigenvalue  $\lambda$  is nonnegative and dominant, i.e.,  $\rho(A) = \lambda$ .*

## Proof.

See Horn & Johnson (2013) *Matrix Analysis*, Corollary 8.1.30, p. 522.  $\square$

# Dominant eigenvalue of dispersal matrix $M$ is always 1

## Corollary

Consider a discrete-time metapopulation map,

$$x_i^{t+1} = \sum_{j=1}^n m_{ij} F(x_j^t), \quad i = 1, \dots, n. \quad (\heartsuit)$$

If solutions of the single patch system,  $x^{t+1} = F(x^t)$ , yield coherent solutions of  $(\heartsuit)$  then 1 is a dominant eigenvalue of  $M$ .

## Proof.

We found earlier that if solutions of the single patch map yield coherent solutions of  $(\heartsuit)$  then  $\sum_{j=1}^n m_{ij} = 1$  for all  $i$ .

This is equivalent to the statement that  $Me = e$ , i.e., 1 is an eigenvalue of  $M$  with eigenvector  $e$ .

But  $e$  is a positive vector, hence by the lemma on the previous slide, 1 is a dominant eigenvalue of  $M$ . □

# Quantities that affect coherence

## Maximum “reproductive rate”:

- Maximum fecundity = maximum reproduction per individual per time step.
- For (single patch) logistic map,  $F(x) = rx(1 - x)$ , maximum fecundity is  $r$ . Note:  $r = \max_x (F'(x))$ .
- Maximum fecundity for any one-dimensional single species map  $F$  is  $r = \max_x (F'(x))$ .
- More generally, single patch map can be multi-dimensional: could represent multiple species (e.g., predator, prey, ...) and/or multiple states per species (e.g.,  $S, E, I, R$ ).
- We can think of  $r = \max_x \|D_x F\|$  as the maximum “reproductive rate” for a multi-dimensional single-patch map.
- $r$  is relevant to coherence.

# Quantities that affect coherence

## Average “reproductive rate”:

- Mean “reproductive rate” over  $T$  time steps is

$$\frac{1}{T} \sum_{t=0}^{T-1} \|D_{\mathbf{x}_t} F\|.$$

- Geometric mean turns out to be more important:

$$\begin{aligned} \left[ \prod_{t=0}^{T-1} \|D_{\mathbf{x}_t} F\| \right]^{1/T} &= \left[ \|D_{\mathbf{x}_0} F\| \|D_{\mathbf{x}_1} F\| \cdots \|D_{\mathbf{x}_{T-1}} F\| \right]^{1/T} \\ &= \left[ \|D_{\mathbf{x}_0} F \cdot D_{\mathbf{x}_1} F \cdots D_{\mathbf{x}_{T-1}} F\| \right]^{1/T} \\ &= \left[ \|D_{\mathbf{x}_0} F^T\| \right]^{1/T} \end{aligned}$$

$$\therefore \log \left[ \prod_{t=0}^{T-1} \|D_{\mathbf{x}_t} F\| \right]^{1/T} = \frac{1}{T} \log \|D_{\mathbf{x}_0} F^T\|$$

# Quantities that affect coherence

## Average “reproductive rate”:

- We actually want the average over the entire trajectory, so we would like to consider

$$\begin{aligned}\lim_{T \rightarrow \infty} \frac{1}{T} \log \|D_{x_0} F^T\| &= \lim_{T \rightarrow \infty} \frac{1}{T} \log \left\| \prod_{t=0}^{T-1} D_{x_t} F \right\| \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \log \|D_{x_t} F\| .\end{aligned}$$

- But this limit may not exist! So consider

$$\chi_{x_0} = \limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \log \|D_{x_t} F\| .$$

which always exists if  $\|D_x F\|$  is bounded  
(true for us because we assume  $r = \max_x \|D_x F\|$  exists).

## Quantities that affect coherence: Summary

- *Degree of spatial coupling:*

Magnitude  $|\lambda|$  of *subdominant eigenvalue*  $\lambda$  of dispersal matrix  $M$

- *Maximum “reproductive rate”:*

$$r = \max_{\mathbf{x}} \|D_{\mathbf{x}}F\|$$

- *Average “reproductive rate”:*

$$\chi_{\mathbf{x}_0} = \limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \log \|D_{\mathbf{x}_t}F\| .$$

This is called the maximum (Lyapunov) *characteristic exponent* of the single patch map.

# Criteria for asymptotic coherence

- *Coherence inevitable:*

*Global asymptotic coherence:* system will eventually synchronize regardless of initial conditions:

$$r|\lambda| < 1$$

- *Coherence possible:*

*Local asymptotic coherence:* system will synchronize if sufficiently close to a coherent attractor:

$$e^{\chi}|\lambda| < 1 \quad \text{i.e., } \chi + \log |\lambda| < 0$$

Note:  $\chi$  is the same for “almost all” initial states  $\mathbf{x}$  (non-trivial to prove)

- *Coherence impossible:*

$$\chi + \log |\lambda| > 0$$



Mathematics  
and Statistics

$$\int_M d\omega = \int_{\partial M} \omega$$

# Mathematics 4MB3/6MB3 Mathematical Biology

Instructor: David Earn

Lecture 9

Space II

Monday 11 November 2019



# Fall 2019 Course Evaluations

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**Open:** Thursday November 21, 10:00AM

**Close:** Thursday December 5, 11:59PM

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[evals.mcmaster.ca](https://evals.mcmaster.ca)

#macevals2019



# Coherence: what we've seen so far

- Quantities that affect coherence
- Coherence criteria

# Global asymptotic coherence (GAC) for equal coupling

**Theorem:**  $r|\lambda| < 1 \implies \text{GAC}$ .

**Proof in case of equal coupling:**

*Dispersal matrix:*

$$m_{ij} = \begin{cases} 1 - m & i = j \\ m/(n-1) & i \neq j \end{cases}$$

*Subdominant eigenvalue:*

$$\lambda = 1 - \left(\frac{n}{n-1}\right)m$$

*General map:*

$$x'_i = \sum_{j=1}^n m_{ij} F(x_j)$$

*Equal coupling case in terms of  $\lambda$ :*

$$= \lambda F(x_i) + (1 - \lambda) \langle F(x_j) \rangle$$

# Global asymptotic coherence (GAC) for equal coupling

*Difference in density between any two patches at next iteration:*

$$\begin{aligned} x'_i - x'_k &= \lambda[F(x_i) - F(x_k)] \\ &= \lambda F'(\xi)(x_i - x_k) \quad (\text{Mean Value Theorem}) \end{aligned}$$

*Hence*  $|x'_i - x'_k| \leq r|\lambda||x_i - x_k|$  *because*  $r = \max_x |F'(x)|$ .

*Therefore,*  $r|\lambda| < 1$  *implies*  $|x_i - x_k| \rightarrow 0$ .

*Q.E.D.*

*Note:* Actually true for very general connectivity matrices  $M$  and multi-dimensional single-patch dynamics  $F(\mathbf{x})$ .

Earn & Levin (2006) *PNAS* **103**, 3968-3971

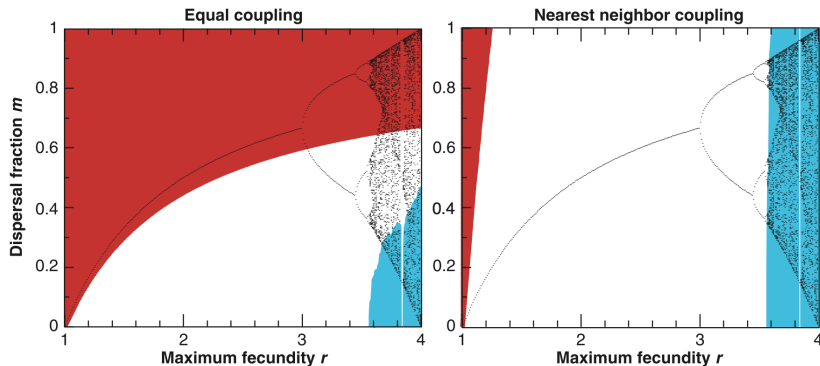
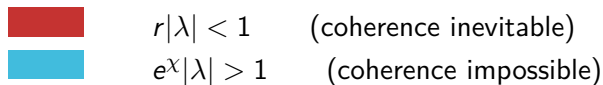
# Theory of local asymptotic coherence (LAC)

- Requires measure theory (e.g., Math 4A03), which allows us to make precise statements like “ $\chi$  is the same for almost all initial states”.
- More significant theoretically than practically, because it yields only *possibility* rather than *probability* of coherence.
- Quasi-global theory attempts to bridge the gap between “probability = 1” and “probability  $> 0$ ”.

McCluskey & Earn (2011) *J. Math. Biol.* **62**, 509–541

# Application of simple coherence criteria

## 10 patch logistic metapopulation



Earn, Levin & Rohani (2000) *Science* **290**, 1360–1364

# Comments on coherence theory

## *Global theory is limited in applicability:*

- Nice theorem guarantees global asymptotic coherence (GAC)

Earn & Levin (2006) *PNAS* 103, 3968-3971

- But hypotheses quite restrictive

## *Local theory is limited in practical power:*

- Applies very generally and aids understanding
- But coherence *possible* doesn't tell how *probable*

## *Quasi-global theory promising:*

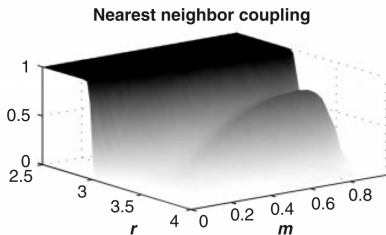
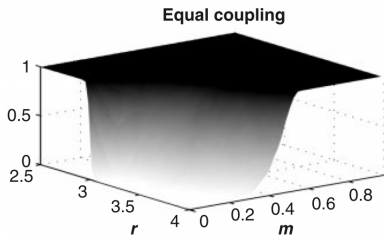
- Show asymptotic approach to coherent manifold from anywhere nearby (rather than just near attractor)
- Via Lozinskii measures

McCluskey & Earn (2011) *J. Math. Biol.* 62, 509-541

# Coherence in “numerical experiments” (simulations)

## 10 patch logistic metapopulation

- Systematically explore representative set of initial conditions and determine probability of coherence within some tolerance, within some specified time
  - e.g., coherence to within 10% within 10 iterations



Earn, Levin & Rohani (2000) *Science* **290**, 1360–1364

- Extremely demanding computationally...*

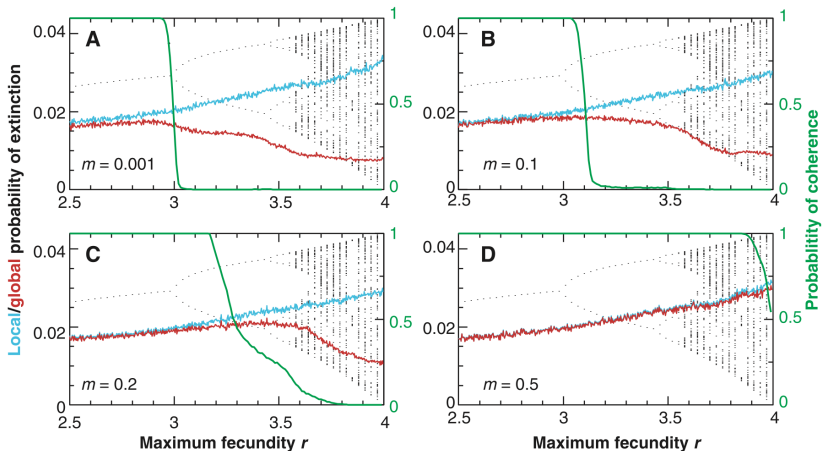


# Connecting coherence to extinction

- Strictly deterministic simulations reveal conditions (model parameter regions) that tend to lead to coherence.
- Coherence  $\neq$  extinction, but intuitively predict:
  - higher probability of coherence  $\implies$ 
    - higher probability of global extinction
    - smaller difference between probabilities of local and global extinction
- Test these predictions by adding *global noise* (randomly occurring events that affect all patches equally) to the deterministic simulations.
- Global noise models *environmental stochasticity* (e.g., weather), which presents a large risk of global extinction because the noise is correlated across all patches.

# Effects of global events that affect all patches equally

*10 patch logistic metapopulation subject to "global noise"*



Earn, Levin & Rohani (2000) *Science* **290**, 1360–1364

# Comments on coherence “experiments”

## *10 patch logistic metapopulation*

- Relationship between model parameters ( $r$ ,  $m$ ) and **probability of coherence** is complicated.
- Predicted relationship between probabilities of coherence and extinction verified.
- Experiments we've discussed ignore *demographic stochasticity*:
  - number of individuals in a population is always an integer.
  - number of offspring an individual produces is a stochastic process.
- Better model would use a stochastic demographic process rather than a deterministic map based on population densities.
- Population models like logistic metapopulation are most relevant to situations where we want to prevent extinctions (conservation of endangered species).

# Relationship to conservation

- For species that we want to conserve, *synchrony is bad!*
- Synchrony prevents *rescue effects*
- Coherence criteria yield method for estimating *risk of synchronization* in ecological systems

Earn, Levin & Rohani (2000) "Coherence and Conservation" *Science* **290**, 1360–1364

# Current Coherence Research

## *Mathematical challenges*

- Strengthen theorems
- Work out details of illustrative examples

## *Biological goals*

- Why do measles and whooping cough have opposite patterns of synchrony?
- What kinds of vaccination strategies can synchronize epidemics worldwide?
- Are such strategies practical to implement?
- Example: global pulse vaccination

# Global pulse vaccination

## *Basic idea*

- International vaccination day each year (or in alternate years, etc.)
- Probably combined with continuous vaccination in countries that already have almost complete coverage

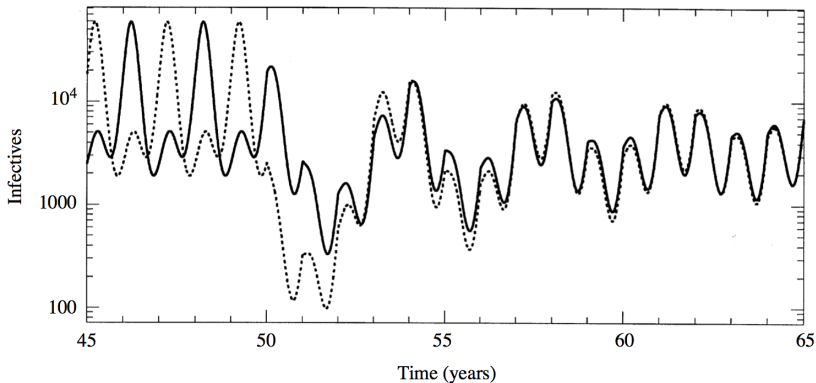
## *Why might this help?*

- Introduce a synchronized periodic forcing
- Has potential to synchronize epidemic troughs
- Pathogen more likely to go extinct globally during synchronized trough

## *Why might this fail?*

- Periodic forcing can have complex dynamical effects. . .

# Example of Synchronization via Pulse Vaccination



SEIR model:  $N_1 = N_2 = 5 \times 10^7$ ,  $\mathcal{R}_0 = 17$ ,  $\sigma^{-1} = 8$  days,  $\gamma^{-1} = 5$  days,  $\alpha = 0.15$ ,  $\epsilon = 0.001$ .

- Immunization started in year 50. Then 20% of susceptible population vaccinated on 1 January each year.

Earn, Rohani & Grenfell (1998) *Proc. R. Soc. Lond.* **265**, 7–10