

23 Metric Spaces II

24 Metric Spaces III

25 Metric Spaces IV

26 Metric Spaces V



Mathematics and Statistics $\int_{M} d\omega = \int_{\partial M} \omega$

Mathematics 3A03 Real Analysis I

Instructor: David Earn

Lecture 22 Metric Spaces Monday 10 March 2025

Announcements

New, exciting topic today...

Metric Spaces

Definition (Absolute Value function)

For any $x \in \mathbb{R}$,

$$|x| \stackrel{\text{def}}{=} \begin{cases} x & \text{if } x \ge 0, \\ -x & \text{if } x < 0. \end{cases}$$

Theorem (Properties of the Absolute Value function)

For all $x, y \in \mathbb{R}$:

- $1 |x| \le x \le |x|.$
- **2** |xy| = |x| |y|.
- 3 $|x+y| \le |x|+|y|$.
- 4 $|x| |y| \le |x y|$.

The metric structure of $\mathbb R$

Definition (Distance function or metric)

The distance between two real numbers x and y is

$$d(x,y) = |x-y| .$$

Theorem (Properties of distance function or metric)

1 $d(x,y) \ge 0$ distances are positive or zero2 $d(x,y) = 0 \iff x = y$ distinct points have distance > 03d(x,y) = d(y,x)distance is symmetric4 $d(x,y) \le d(x,z) + d(z,y)$ the triangle inequality

<u>Note</u>: Any function satisfying these properties can be considered a "distance" or "metric".

Given d(x, y) = |x - y|, the properties of the distance function are equivalent to:

Theorem (Metric properties of the absolute value function)

For all $x, y \in \mathbb{R}$:

- **1** $|x| \ge 0$
- $2 |x| = 0 \iff x = 0$

3 |x| = |-x|

4 $|x + y| \le |x| + |y|$ (the triangle inequality)

Slick proof of the triangle inequality

Theorem (The Triangle Inequality for the standard metric on \mathbb{R})

 $|x + y| \le |x| + |y|$ for all $x, y \in \mathbb{R}$.

Proof.

Let s = sign(x + y). Then

$$|x + y| = s(x + y) = sx + sy \le |x| + |y|$$
,

as required.

A non-standard metric on $\mathbb R$

Example (finite distance between every pair of real numbers)

Let $f(x) = \frac{x}{1+x}$, and define d(x, y) = f(|x - y|). Prove that d(x, y) can be interpreted as a distance between x and y because it satisfies all the properties of a metric.

Proof: The only metric property that is non-trivial to prove is the triangle inequality. Note that f(x) is an increasing function on $[0, \infty)$, so the usual triangle inequality, $|x - y| \le |x - z| + |z - y|$, implies

$$f(|x-y|) \leq f(|x-z| + |z-y|) = \frac{|x-z| + |z-y|}{1+|x-z| + |z-y|}$$

= $\frac{|x-z|}{1+|x-z| + |z-y|} + \frac{|z-y|}{1+|x-z| + |z-y|}$
 $\leq \frac{|x-z|}{1+|x-z|} + \frac{|z-y|}{1+|z-y|} = f(|x-z|) + f(|z-y|)$

i.e., $d(x, y) \le d(x, z) + d(z, y)$.

Poll

Go to

https://www.childsmath.ca/childsa/forms/main_login.php

- Click on Math 3A03
- Click on Take Class Poll
- Fill in poll Metric spaces: Is "= vs \neq " a metric?

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Example (Discrete metric on \mathbb{R})

Let
$$d(x,y) = \begin{cases} 0 & x = y, \\ 1 & x \neq y. \end{cases}$$
 Is d a metric on \mathbb{R} ?

By definition, d(x, y) is non-negative, zero iff x = y, and symmetric. For the triangle inequality, if x = y then d(x, y) = 0so the inequality holds for any z. If $x \neq y$ then d(x, y) = 1, and at least one of x and y must not equal z, so the inequality says either $1 \leq 1$ or $1 \leq 2$.

Example (Discrete metric on any set X)

The argument that d(x, y) is a metric on \mathbb{R} has nothing to do with \mathbb{R} specifically. d(x, y) is a metric on any set X.

Definition (Metric space)

A *metric space* (X, d) is a non-empty set X together with a distance function (or *metric*) $d : X \times X \to \mathbb{R}$ satisfying

1 $d(x,y) \ge 0$ distances are positive or zero2 $d(x,y) = 0 \iff x = y$ distinct points have distance > 03d(x,y) = d(y,x)distance is symmetric4 $d(x,y) \le d(x,z) + d(z,y)$ the triangle inequality

Much of our analysis of sequences of real numbers and topology of \mathbb{R} generalizes to any metric space. Very often, definitions and proofs depend only on the the existence of a metric, not on |x| specifically. Many useful inferences can be made by identifying a metric on a space of interest.

Example (Metric spaces (X, d))

- X = Q, with the standard metric d(x, y) = |x y|.
 As Q ⊂ R, each condition for d is satisfied in Q.
 How different is (Q, d) from (R, d) ?
- $X = \mathbb{N}$, with the standard metric d(x, y) = |x y|. As $\mathbb{N} \subset \mathbb{R}$, each condition for *d* is satisfied in \mathbb{N} .

•
$$X = \mathbb{R}^2$$
 with $d(x, y) = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2}$, where we write the vectors $x = (x_1, x_2)$, $y = (y_1, y_2) \in \mathbb{R}^2$.

•
$$X = \mathbb{R}^n$$
 with $d(x, y) = \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$, where $x = (x_1, ..., x_n), y = (y_1, ..., y_n) \in \mathbb{R}^n$.

This metric on \mathbb{R}^n is called the *Euclidean distance*.

Metrics from norms

The Euclidean metric on \mathbb{R}^n is the (Euclidean) length of the difference of two vectors. This connection between length and distance generalizes to any vector space in which *length* is defined.

Definition (Norm)

A *norm* on a vector space X is a real-valued function on X such that if $x, y \in X$ and $\alpha \in \mathbb{R}$ then

1 $||x|| \ge 0$ and ||x|| = 0 iff x is the zero element in X;

2
$$\|\alpha x\| = |\alpha| \|x\|;$$

3
$$||x+y|| \le ||x|| + ||y||.$$

A vector space X equipped with a norm $\|\cdot\|$ is said to be a *normed* vector space. Any norm $\|\cdot\|$ induces a metric d via

$$d(x,y) = \|x-y\|.$$

Proving that a function is a norm is not necessarily easy. Let's try for the Euclidean norm...To that end, recall the notion of inner product ...

Distance

Norms from inner products

Definition (Inner product)

An *inner product* on a vector space V over \mathbb{R} is a function

$$\langle \cdot, \cdot \rangle : V \times V \to \mathbb{R}$$

such that for all $u, v, w \in V$ and all scalars $\alpha \in \mathbb{R}$:

- $(u, v) = \overline{\langle v, u \rangle}$ conjugate symmetry
- 2 $\langle \alpha u + v, w \rangle = \alpha \langle u, w \rangle + \langle v, w \rangle$ linearity in 1st argument

3
$$\langle v, v \rangle \ge 0$$
 with equality iff $v = 0$ positive definiteness

A vector space equipped with an inner product is called an *inner product space*.

Definition (Inner Product Norm)

The norm induced by an inner product $\langle \cdot, \cdot \rangle$ is $||u|| = \sqrt{\langle u, u \rangle}$.

Norms from inner products

Theorem (Cauchy-Schwarz inequality)

Let V be a (real) inner product space with inner product $\langle\cdot,\cdot\rangle$. For all vectors u, v \in V, we have

$$|\langle u,v\rangle| \leq ||u|| ||v||$$

where $||u|| = \sqrt{\langle u, u \rangle}$ is the norm induced by the inner product.

Proof.

The standard proof begins with an idea that probably took someone a long time to think of: Since $\langle v, v \rangle \ge 0$ for any $v \in V$, for any $t \in \mathbb{R}$ we have

$$0 \leq \langle u + tv, u + tv \rangle = \langle u, u \rangle + t \langle u, v \rangle + t \langle v, u \rangle + t^{2} \langle v, v \rangle$$
$$= \langle u, u \rangle + 2t \langle u, v \rangle + t^{2} \langle v, v \rangle$$

This is a quadratic polynomial in t, which is non-negative for all $t \in \mathbb{R}$. Hence, this quadratic has at most one real root. Consequently, its discriminant is non-positive, *i.e.*, $(2 \langle u, v \rangle)^2 - 4 \langle u, u \rangle \langle v, v \rangle \leq 0$.

continued...

Norms from inner products

Proof of Cauchy-Schwarz inequality (continued).

Simplifying the non-positive discriminant condition, we have

$$(\langle u, v \rangle)^2 \leq \langle u, u \rangle \langle v, v \rangle \; .$$

Taking square roots, we have

 $|\langle u,v\rangle| \leq ||u|| ||v|| ,$

as required.

How might you come up with such a proof?

Perhaps by guessing the result (based on knowing it in $\mathbb{R}^2)$ and then working backwards.



Mathematics and Statistics $\int_{M} d\omega = \int_{\partial M} \omega$

Mathematics 3A03 Real Analysis I

Instructor: David Earn

Lecture 23 Metric Spaces II Wednesday 12 March 2025

Instructor: David Earn Mathematics 3A03 Real Analysis

Participation deadline for Assignment 4 was at 11:25am today.

Last time. . .

- Introduction to metric spaces
 - Critical ingredient: the triangle inequality
- Cauchy-Schwarz inequality

(proved for real inner product spaces)

Norms from inner products

If X is an inner product space, then Cauchy-Schwarz allows us to prove that the induced norm really is a norm (*i.e.*, satisfies the triangle inequality). For $x, y \in X$, we have

$$\begin{aligned} \|x + y\|^2 &= \langle x + y, x + y \rangle \\ &= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle \\ &= \|x\|^2 + \|y\|^2 + 2 \langle x, y \rangle \\ &\leq \|x\|^2 + \|y\|^2 + 2 \|x\| \|y\| \\ &= (\|x\| + \|y\|)^2 \end{aligned}$$

 $\implies \qquad \|x+y\| \leq \|x\|+\|y\| \ .$

In particular, \mathbb{R}^n with the usual "dot product" $\langle x, y \rangle = \sum_{i=1}^n x_i y_i$ induces the Euclidean norm $\|\cdot\|_2$, which therefore really is a norm, and $d(x, y) = \|x - y\|_2$ really is a metric (the Euclidean distance). What about other norms induced by inner products?

Other metric spaces induced by inner products

We are accustomed to finite vectors:

$$egin{aligned} & x = (x_1, x_2) \in X = \mathbb{R}^2 \ & x = (x_1, x_2, x_3) \in X = \mathbb{R}^3 \ & x = (x_1, x_2, \dots, x_n) \in X = \mathbb{R}^n \end{aligned}$$

We can think of a sequence as an infinite vector:

$$x = (x_1, x_2, \ldots) \in X = \big\{ \{x_n\} : n \in \mathbb{N} \big\}$$

The points in this space (X) are infinite-dimensional vectors.

We can think of an infinite vector as a function:

$$x_n = f(n) \implies (x_1, x_2, \ldots) = (f(1), f(2), \ldots)$$

The points in this space are functions: $X = \{f \mid f : \mathbb{N} \to \mathbb{R}\}.$

So we can generalize to other spaces via functions, e.g.,

$$C[0,1] = \{f : [0,1] \to \mathbb{R} \mid f \text{ continuous}\}$$

All of the above spaces have a natural inner product, and hence a natural norm and metric.

Other metric spaces induced by inner products

Inner products that convert the spaces on the previous slide into (Euclidean) metric spaces:

$$\mathbb{R}^n: \quad \langle x, y \rangle = \sum_{i=1}^n x_i y_i$$

$$\ell^2(\mathbb{R})$$
: $\langle x,y\rangle = \sum_{i=1}^{\infty} x_i y_i$

$$C[a,b]:$$
 $\langle f,g\rangle = \int_a^b f(x)g(x) \, dx$

<u>Note</u>: ℓ^2 includes only *square-summable* sequences:

$$\sum_{n=1}^{\infty} x_n^2 < \infty$$

Do we need to specify that C[a, b] contains only **square-integrable** functions?

Metrics from norms

Example (Taxicab distance)

Taxicab norm on \mathbb{R}^n



$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

In taxicab geometry, the lengths of the **red**, **blue**, green, and yellow paths all equal 12, the taxicab distance between the opposite corners, and all four paths are <u>shortest paths</u>. Instead, in Euclidean geometry, the **red**, **blue**, and **yellow** paths still have length 12 but the green path is the unique shortest path, with length equal to the Euclidean distance between the opposite corners, $6\sqrt{2} \approx 8.49$.

Image and caption from Wikipedia article on "Taxicab geometry".

<u>Note</u>: The green path <u>can</u> be followed. All the points of \mathbb{R}^2 are still present when we measure distance with the taxicab metric. Any monotonic curve path that joins the two points can be approximated by an arbitrarily fine grid, and will have the same length. The metric does not impose a particular grid.

Metrics from norms

Example (*p*-metric)
p-norm on
$$\mathbb{R}^n$$
 (for $p \ge 1$) $||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$.
• $p = 1$ is the taxicab norm.
• $p = 2$ is the Euclidean norm.
What happens as $p \to \infty$? For any $x \in \mathbb{R}^n$, we have
 $||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}} = |x_k| \left(\sum_{i=1}^n \left|\frac{x_i}{x_k}\right|^p\right)^{\frac{1}{p}} \quad (|x_k| > |x_i| \ \forall i \neq k)$
 $= |x_k| \left(1 + \sum_{i \neq k} \left|\frac{x_i}{x_k}\right|^p\right)^{\frac{1}{p}} \xrightarrow{p \to \infty} |x_k|$
What further work is required if $\nexists k \Rightarrow |x_k| > |x_i| \ \forall i \neq k$?

Therefore, we define $\left\|\cdot\right\|_{\infty}$ to be

Max norm on \mathbb{R}^n

$$\|x\|_{\infty} = \max_{1 \le i \le n} |x_i|$$

Poll

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Metrics from norms

Example (p-metric)

Proving that p = 1 and $p = \infty$ yield norms is a *good exercise*.

Only p = 2 is induced by an inner product.

That the *p*-norms for $p \neq 1, 2, \infty$ are norms is harder to prove (but true), so

$$d_p(x,y) = \left\|x - y\right\|_p$$

is a metric on \mathbb{R}^n for any $p \ge 1$.

We can generalize the notion of "neighbourhood of a point" to any metric space:

Definition (Open ball)

Let (X, d) be a metric space. If $x_0 \in X$ and r > 0 then the *open* ball of radius r about x_0 is

$$B_r(x_0) = \{x \in X : d(x, x_0) < r\}.$$

 x_0 is said to be the *centre* of $B_r(x_0)$.

<u>Note</u>: The notation $B(x_0, r)$ is also common (and used in TBB).

Definition (Neighbourhood)

A *neighborhood* of x is any set that contains an open ball $B_r(x)$ for some r > 0.

Example (Open balls in metric spaces)

- In the metric space (\mathbb{R} , standard), i.e., \mathbb{R} with d(x, y) = |x y|, $B_r(x) = (x - r, x + r)$, an open interval of length 2*r* centred at *x*.
- In ℝⁿ with Euclidean metric d(x, y) = ||x y||₂, B_r(x) has a spherical boundary (circular boundary if n = 2).
- In \mathbb{R}^n with a *p*-norm $\|\cdot\|_p$, the ball is not spherical. For \mathbb{R}^2 with the Taxicab metric $d(x, y) = \|x y\|_1$, $B_r(x)$ is diamond shaped, and for \mathbb{R}^2 with the Max norm $\|\cdot\|_{\infty}$, $B_r(x)$ is a square. We write $B_r^p(x)$ for balls in the *p*-norm ("*p*-balls").



Example (*p*-norm inequalities and containments)

The following inequalities relate the various *p*-norms on \mathbb{R}^n ,

$$\|x\|_{\infty} \le \|x\|_{2} \le \|x\|_{1} \le n \|x\|_{\infty}, \text{ and } \|x\|_{1} \le \sqrt{n} \|x\|_{2}.$$

A good exercise.

Balls in the norm $\|\cdot\|_p$ are often written $B_r^p(x)$. The inequalities above imply that the following sets are *nested*:

$$B^2_{r/n}(x) \subset B^\infty_{r/n}(x) \subset B^1_r(x) \subset B^2_r(x) \subset B^\infty_r(x).$$

Another good exercise.

Example (Balls in the discrete metric)

For any set X, in the *discrete metric* the balls are simple, but strange. If $0 < r \le 1$ then $B_r(x) = \{x\}$, a single point! If r > 1 then $B_r(x) = X$, the whole space! You can't be "close" to a point x unless you are at x itself!





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Mathematics 3A03 Real Analysis I

Instructor: David Earn

Lecture 25 Metric Spaces III Monday 17 March 2025

Announcements

Discussion of metrics so far...

- Metrics induced by norms, e.g., p-norms
- Metrics from norms induced by inner products
- Metric on any set: discrete metric
- Balls (*p*-balls, discrete balls)

<u>Note</u>:

I added a note to the slide on the taxicab metric.

Definition (Convergence of a sequence in a metric space)

Let (X, d) be any metric space. A sequence $(x_n)_{n \in \mathbb{N}}$ converges to $x \in X$, written $x_n \xrightarrow{n \to \infty} x$ or $\lim_{n \to \infty} x_n = x$, if:

$$\forall \varepsilon > 0, \ \exists N \in \mathbb{N} \ \) \ \ d(x_n, x) < \varepsilon \quad \forall n \ge N.$$

If the sequence does not converge to any $x \in X$, we say it *diverges*.

Equivalently, $x_n \xrightarrow{n \to \infty} x$ if, for any ball $B_{\varepsilon}(x)$ centered at x, the sequence (x_n) lies inside that ball eventually $(\exists N \in \mathbb{N} \text{ such that } x_N \in B_{\varepsilon}(x))$, and stays inside it $(x_n \in B_{\varepsilon}(x) \ \forall n > N)$, *i.e.*,

$$\forall \varepsilon > 0, \exists N \in \mathbb{N} \quad) \quad x_n \in B_{\varepsilon}(x) \quad \forall n \ge N.$$

Definition (Boundedness in a metric space)

In any metric space (X, d), a sequence (x_n) is **bounded** if there exists $x_0 \in X$ and r > 0 such that $x_n \in B_r(x_0)$ for all $n \in \mathbb{N}$.

Theorem

In any metric space (X, d), any convergent sequence is bounded.

<u>*Note:*</u> The converse is FALSE. *e.g.*, $x_n = (-1)^n$ in (\mathbb{R} , standard).

Proof.

Taking $\varepsilon = 1$ (or any particular value) in the definition of convergence, since $x_n \xrightarrow{n \to \infty} x$ in (X, d), $\exists N \in \mathbb{N}$ with $d(x_n, x) < \varepsilon = 1$, $\forall n \ge N$, *i.e.*, $x_n \in B_1(x)$, $\forall n \ge N$. The earlier elements of the sequence, x_1, \ldots, x_{N-1} , are a finite collection, so we can choose r > 0 so that

$$r > \max\{d(x_1, x), d(x_2, x), \dots, d(x_{N-1}, x), 1\}.$$

With this r, $x_n \in B_r(x)$ holds $\forall n \in \mathbb{N}$. So (x_n) is bounded.

Definition (Interior point)

 $x \in E \subseteq X$ is an *interior point* of the set E in the metric space (X, d) if x lies in an open ball that is contained in E, *i.e.*, $\exists \varepsilon > 0 \Rightarrow B_{\varepsilon}(x) \subset E.$

Definition (Interior of a set)

If $E \subseteq X$ then the *interior* of E, denoted int(E) or E° , is the set of all interior points of E.

<u>Note</u>:

- $x \in E^{\circ}$ means not only that $x \in E$, but that there is an entire open ball $B_{\varepsilon}(x) \subset E$.
- For any smaller radius, 0 < r < ε, we have x ∈ B_r(x) ⊆ B_ε(x) ⊆ E, so the choice of ε is not unique for an interior point.

Definition (Open set)

A set $E \subseteq X$ is *open* if every point of *E* is an interior point.

Example (Upper half-plane in $(\mathbb{R}^2, \text{Euclidean})$)

Let $W = \{x = (x_1, x_2) : x_2 > 0\}$. Then $\forall x \in W$, if $0 < \varepsilon < x_2$ then $B_{\varepsilon}(x) \subset W$. Thus all $x \in W$ are interior points. So W is an open set.

Example (Any set in (X, discrete))

(X, discrete) means X is a non-empty set and d is the discrete metric d. So, $\forall x \in X$,

$$\mathcal{B}_arepsilon(x) = egin{cases} \{x\}, & ext{if } 0 < arepsilon \leq 1, \ X, & ext{if } arepsilon > 1. \end{cases}$$

Therefore, for any subset $E \subseteq X$ and for any point $x \in E$, $B_1(x) = \{x\} \subseteq E$, so every point of any set E is an interior point, so <u>all</u> sets in the discrete metric are open sets!

Definition (Closed set)

A set $F \subseteq X$ is **closed** if F^c is open.

Example (Lower half-plane in $(\mathbb{R}^2, \text{Euclidean})$)

Let $Z = \{x = (x_1, x_2) : x_2 \le 0\}$. Then $Z = W^c$, where W is the (open) upper half-plane. So Z is a closed set.

<u>Note</u>: In (\mathbb{R}^2 , Euclidean), a half-plane is open or closed depending on whether none or all of the *x*-axis is included. If neither none nor all of the *x*-axis is included then the half-plane is neither open nor closed.

Example (Any set in (X, discrete))

Any set $E \subseteq X$ is open. So given any $F \subseteq X$, $F^c \subseteq X$ so F^c is open. Hence F is closed. So <u>all</u> sets are *both open and closed* with respect to the discrete metric.
When studying $X = \mathbb{R}$, we defined closed sets differently. Could we have used the same definition for a general metric space?

Definition (Accumulation Point or Limit Point or Cluster Point)

If $E \subseteq X$ in a metric space (X, d) then x is an *accumulation point* of E if every neighbourhood of x contains infinitely many points of E,

i.e., $\forall \varepsilon > 0$ $B_{\varepsilon}(x) \cap (E \setminus \{x\}) \neq \emptyset$.

Equivalently, $x \in X$ is an accumulation point of the set E if and only if there exists a sequence $(x_n)_{n\in\mathbb{N}}$ with $x_n \in E \ \forall n \in \mathbb{N}$, such that $x_n \neq x \ \forall n$ and $x_n \xrightarrow{n \to \infty} x$.

Theorem (Closed sets in a metric space)

A set $F \subseteq X$ in a metric space (X, d) is closed if and only if F contains all its accumulation points.

Proof.

First, suppose F is closed, and that $x \in X$ is an accumulation point of F. If $x \notin F$, then $x \in F^c$, which is open. Therefore, $\exists \varepsilon > 0$ such that $B_{\varepsilon}(x) \subset F^c$, *i.e.*, $B_{\varepsilon}(x) \cap F = \emptyset$. But this contradicts xbeing an accumulation point of F. So we must have $x \in F$.

Conversely, suppose *F* contains all its accumulation points. Then, if $z \in F^c$, *z* cannot be an accumulation point of *F*. But for any $\varepsilon > 0$, $z \in B_{\varepsilon}(z)$, so $\exists \varepsilon > 0$ for which $B_{\varepsilon}(z) \cap F = \emptyset$, *i.e.*, $B_{\varepsilon}(z) \subset F^c$. Hence F^c is open, so *F* is closed.

Theorem (Properties of open sets in a metric space (X, d))

- **1** The sets X and \varnothing are open.
- 2 Any intersection of a finite number of open sets is open.
- 3 Any union of an arbitrary collection of open sets is open.
- **4** The complement of an open set is closed.

Theorem (Properties of closed sets in a metric space (X, d))

- The sets X and Ø are closed.
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Example (Set differences of balls)

Suppose $0 < r_1 < r_2$ and (X, d) is a metric space. If $x \in X$, is it necessarily true that $B_{r_2}(x) \setminus B_{r_1}(x)$ is open or closed?

No, it depends on the metric *d*. If $(X, d) = (\mathbb{R}^n, \text{Euclidean})$ then $B_{r_2}(x) \setminus B_{r_1}(x)$ is neither open nor closed, *e.g.*, in \mathbb{R}^1 ,

$$B_{r_2}(x) \setminus B_{r_1}(x) = (x - r_2, x + r_2) \setminus (x - r_1, x_+ r_1) = (x - r_2, x - r_1] \cup [x + r_1, x + r_2).$$

In contrast, if $(X, d) = (\mathbb{R}^n, \text{discrete})$ then $B_{r_2}(x) \setminus B_{r_1}(x)$ is open since any set in (X, d) is both open and closed.

In general, if A and B are sets then

$$A \setminus B = A \cap B^{\mathsf{c}},$$

so if A and B are both open, and B is also closed, then $A \setminus B$ is open.

Definition (Isolated point)

If $x \in E \subseteq X$ in a metric space (X, d) then x is an *isolated point* of E if there is a neighbourhood of x for which the only point in E is x itself, *i.e.*,

$$\exists \varepsilon > 0 \quad \} \quad B_{\varepsilon}(x) \cap E = \{x\}.$$

Example

Consider the metric space (X, d) = ([0, 1], standard). What are the isolated points of (X, d)?

There are no isolated points!

```
Now suppose (X, d) = ([0, 1], \text{discrete}).
What are the isolated points of (X, d)?
```

All points are isolated!



Mathematics and Statistics $\int_{M} d\omega = \int_{\partial M} \omega$

Mathematics 3A03 Real Analysis I

Instructor: David Earn

Lecture 26 Metric Spaces IV Wednesday 19 March 2025

Announcements

Last time...

More definitions and examples related to metric topology

Definition (Closure of a set)

If (X, d) is a metric space and $E \subseteq X$ then the *closure* of *E*, denoted \overline{E} , is the smallest closed set that contains *E*.

 $\therefore \overline{E} \text{ is closed, } E \subseteq \overline{E}, \text{ and if } F \text{ is closed and } E \subseteq F, \text{ then } \overline{E} \subseteq F.$

Theorem

 $x \in \overline{E} \iff x$ is either an element of E or an accumulation point of E. i.e., $x \in \overline{E} \iff \forall \varepsilon > 0, \ B_{\varepsilon}(x) \cap E \neq \emptyset$.

Proof.

 $\begin{array}{l} (\longleftarrow) \text{ Suppose } \forall \varepsilon > 0 \ B_{\varepsilon}(x) \cap E \neq \varnothing. \text{ In order to derive a contradiction,} \\ \text{assume } x \notin \overline{E}. \quad \text{Then } x \in (\overline{E})^c, \text{ which is open, so } \exists \varepsilon > 0 \text{ such that} \\ B_{\varepsilon}(x) \subseteq (\overline{E})^c, \text{ i.e., } B_{\varepsilon}(x) \cap \overline{E} = \varnothing. \text{ But } E \subset \overline{E}, \text{ so } B_{\varepsilon}(x) \cap E = \varnothing. \Rightarrow \Leftrightarrow \\ (\Longrightarrow) \text{ Suppose } x \in \overline{E} \text{ and, in order to derive a contradiction, suppose } \exists \varepsilon > 0 \\ \end{pmatrix} \ B_{\varepsilon}(x) \cap E = \varnothing. \text{ Then } E \subseteq (B_{\varepsilon}(x))^c. \text{ Hence } \overline{E} \subseteq (\overline{B_{\varepsilon}(x)})^c = (B_{\varepsilon}(x))^c. \\ \text{But } x \in \overline{E} \text{ and } x \notin (B_{\varepsilon}(x))^c. \Rightarrow \Leftrightarrow \ldots \forall \varepsilon > 0, \ B_{\varepsilon}(x) \cap E \neq \varnothing. \end{array}$

Example (Cubic balls in \mathbb{R}^n)

In \mathbb{R}^n with the max norm $\|\cdot\|_{\infty}$, the distance between $x = (x_1, \ldots, x_n)$ and $y = (y_1, \ldots, y_n)$ is

$$d(x,y) = ||x-y||_{\infty} = \max\{|x_i - y_i| : 1 \le i \le n\}.$$

Consider the set $E \subset \mathbb{R}^n$, where

$$E = \{ x \in \mathbb{R}^n : 0 < x_i < 1, \ \forall i \in \{1, \dots, n\} \}.$$

What are the interior E° and closure \overline{E} of the set E?

- n = 1: E = (0, 1), an open interval. $E^{\circ} = (0, 1) = E$. $\overline{E} = [0, 1]$.
- n = 2: $E = (0, 1) \times (0, 1)$, an open square (an open ball in this metric). $E^{\circ} = (0, 1)^2 = E$. $\overline{E} = [0, 1]^2$.
- n > 2: $E = (0, 1)^n$, an open *n*-cube (an open ball in this metric). $E^\circ = (0, 1)^n = E$. $\overline{E} = [0, 1]^n$.

When we imagine an *n*-cube for n > 3, we are probably thinking about n = 3 in our minds. But we can easily represent individual points in \mathbb{R}^n in the plane. *How*?

Example (Cubic balls in \mathbb{R}^n)

Suppose $x, y \in E \subset \mathbb{R}^{28}$, $d(x, y) = ||x - y||_{\infty}$.



The vertical **black line** indicates the distance between *x* and *y*.

<u>Note</u>: The same picture works for $\ell^{\infty}(\mathbb{R})$, the space of sequences that are bounded, and in which the norm is defined by sup rather than max.

For the space of continuous functions on a closed interval [a, b], we defined the Euclidean norm via the standard inner product. We can also define a *p*-norm on this space for any $p \ge 1$,

$$\|f\|_{p} = \left(\int_{a}^{b} |f(x)|^{p} dx\right)^{1/p}.$$

As in finite dimensions, $\lim_{p \to \infty} \left\| f \right\|_p = \left\| f \right\|_\infty$, where

$$\|f\|_{\infty} \equiv \sup\{|f(x)|: a \le x \le b\} = \max\{|f(x)|: a \le x \le b\}.$$

<u>Note</u>: In the metric space (C[a, b], d) with $d(f, g) = ||f - g||_{\infty}$, convergence of sequences of "points", $f_n \xrightarrow{n \to \infty} f$, implies $f_n \xrightarrow{n \to \infty} f \in C[a, b]$.

Example

In the metric space C([a, b]), with distance given by the sup-norm,

$$d(f,g) = ||f-g||_{\infty} = \sup\{|f(x)-g(x)|: a \le x \le b\},$$

let

$$E = \{ f \in C([a, b]) : 0 < f(x) < 1, \forall x \in [a, b] \}.$$

What are the interior E° and closure \overline{E} of the set E?



Example (Cubic balls in C[0,1])

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Suppose f, g \in E \subset C[0, 1], d(f, g) = ||f - g||_{\infty}.
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Example (Cubic balls in C[0,1])

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Suppose f, g \in E \subset C[0, 1], d(f, g) = ||f - g||_{\infty}.
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Example (Cubic balls in C[0,1])

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Suppose f, g \in E \subset C[0, 1], d(f, g) = ||f - g||_{\infty}.
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Example $(E^{\circ} \text{ and } \overline{E} \text{ for } E = \{f \in C([a, b]) : 0 < f(x) < 1 \quad \forall x \in [a, b]\})$

If $f \in C([a, b])$ then f is continuous on [a, b] so, by the Extreme Value Theorem, f attains its minimum and maximum values on [a, b], say at $u, v \in [a, b]$. Since $f(x) \in (0, 1)$ for all $x \in [a, b]$, the extreme values, f(u) and f(v), must also be in the open interval (0, 1). Therefore,

$$0 < f(u) \leq f(x) \leq f(v) < 1, \quad \forall x \in [a,b]. \tag{()}$$

Thus, the range of f is $[f(u), f(v)] \subset (0, 1)$. There is a gap (a finite interval) that "insulates" f from the extreme values (0 and 1).

Let $\varepsilon = \min\{f(u), 1 - f(v)\}$. Then $\varepsilon > 0$. Now consider $g \in B_{\varepsilon}(f) \subset C([a, b])$.

Then:
$$\|g - f\|_{\infty} < \varepsilon$$

 $\implies \max\{|g(x) - f(x)| : 0 \le x \le 1\} < \varepsilon$
 $\implies |g(x) - f(x)| < \varepsilon \quad \forall x \in [0, 1]$
 $\implies -\varepsilon < g(x) - f(x) < \varepsilon \quad \forall x \in [0, 1]$
 $\implies f(x) - \varepsilon < g(x) < f(x) + \varepsilon \quad \forall x \in [0, 1]$

Example $(E^{\circ} \text{ and } \overline{E} \text{ for } E = \{f \in C([a, b]) : 0 < f(x) < 1 \quad \forall x \in [a, b]\})$

Now using (\heartsuit) , we have

 $0 \leq f(u) - \varepsilon \leq f(x) - \varepsilon < g(x) < f(x) + \varepsilon \leq f(v) + \varepsilon \leq 1, \quad \forall x \in [a, b],$

from which we conclude that $g \in E$.

Since g was an arbitrary "point" in $B_{\varepsilon}(f)$, it follows that $B_{\varepsilon}(f) \subseteq E$, so any $f \in E$ is an interior point, so E is open and $E^{\circ} = E$.

What about \overline{E} , the closure of E?

We will show that the closure of E is the set

$$F = \{f \in C([a, b]) : 0 \le f(x) \le 1, \forall x \in [a, b]\}.$$

We will show $\overline{E} \subseteq F$ and then $F \subseteq \overline{E}$.

(♠)

Example (E° and \overline{E} for $E = \{f \in C([a, b]) : 0 < f(x) < 1 \quad \forall x \in [a, b]\}$)

 $(\overline{E} \subseteq F)$ First, consider any sequence $(f_n)_{n \in \mathbb{N}}$ with $f_n \in E$, $\forall n \in \mathbb{N}$, and suppose $f_n \xrightarrow{n \to \infty} f$ in the sup-norm, *i.e.*, $f_n \xrightarrow{n \to \infty}_{unif} f$. Since uniform convergence implies pointwise convergence, and $f_n(x) \in (0, 1)$, we must have $0 \le f(x) \le 1$, $\forall x \in \mathbb{N}$, and since $f_n \xrightarrow{n \to \infty}_{unif} f$, we know $f \in C([a, b])$, so $f \in F$. Since f is a limit point of E and any limit point of E must lie in \overline{E} , we must have $\overline{E} \subseteq F$.

$$(F \subseteq \overline{E}) \quad \text{Suppose } f \in F, \text{ and define the sequence } f_n \in E \text{ by}$$
$$f_n(x) = \begin{cases} 1 - \frac{1}{n}, & \text{if } f(x) > 1 - \frac{1}{n}, \\ f(x), & \text{if } \frac{1}{n} \leq f(x) \leq 1 - \frac{1}{n}, \\ \frac{1}{n}, & \text{if } f(x) < \frac{1}{n}. \end{cases}$$

By construction, $f_n \xrightarrow{n \to \infty}_{\text{unif}} \neq f$, and so f is a limit point of E so (by the theorem about closures again) $F \subseteq \overline{E}$. (Note: $f_n \to f$ is illustrated in the next few slides.)

Therefore, $F = \overline{E}$.











Illustration of $f_n \rightarrow f$ for $f_n \in E$, $f \notin E$, $f \in F$



Illustration of $f_n \rightarrow f$ for $f_n \in E$, $f \notin E$, $f \in F$









Mathematics and Statistics $\int_{M} d\omega = \int_{\partial M} \omega$

Mathematics 3A03 Real Analysis I

Instructor: David Earn

Lecture 27 Metric Spaces V Friday 21 March 2025

Last time...

- Last time: interior and closure
- I added some graphs illustrating $f_n \to f$ in the construction that proved $F \subseteq \overline{E}$ at the end of the discussion of E° and \overline{E} for $E \subset C[a, b]$.

Boundary

Definition (Boundary Point)

If $E \subseteq X$ in a metric space (X, d), then x is a **boundary point** of E if every neighbourhood of x contains at least one point of E and at least one point not in E, *i.e.*,

$$orall arepsilon > 0 \qquad B_arepsilon(x) \cap E
eq arnothing \ \wedge \qquad B_arepsilon(x) \cap (X \setminus E)
eq arnothing \ arnothing \
ightarrow \ arnothing \$$

Definition (Boundary)

If $E \subseteq X$ then the **boundary** of *E*, denoted ∂E , is the set of all boundary points of *E*.

Example (Properties of boundary of E in a metric space (X, d))

- For any $E \subset X$
 - $\partial E = \overline{E} \setminus E^{\circ};$
 - ∂E is a closed set;
 - *E* is closed if and only if $\partial E \subseteq E$.

Excellent exercises...

Example $(E^{\circ}, \overline{E}, \partial E \text{ for } E = (0, 1)^{\infty} \subset \ell^{\infty})$

In the metric space ℓ^{∞} , *i.e.*, bounded sequences (x_n) with distance given by the sup-norm,

$$d(x,y) = ||x-y||_{\infty} = \sup\{|x_n-y_n|: n \in \mathbb{N}\},\$$

let

$$E = \{(x_n) \in \ell^{\infty} : 0 < x_n < 1, \forall n \in \mathbb{N}\}.$$

What are the interior E° , closure \overline{E} , and boundary ∂E of the set E?

Please do poll: Metric spaces: ℓ^{∞}

Consider the following points in ℓ^{∞} . Are they in E? Are they in E°? Are they in \overline{E} ? Are they in ∂E ?

$$(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \dots) ((-1)^n)_n$$

- (0, 0, 0, . . .)
- **(**0, 1, 0, 1, . . . **)**

€N

$$\left(\frac{1}{n}\right)_{n\in\mathbb{N}}$$

$$\left(\frac{1}{n+1}\right)_{n\in\mathbb{N}}$$

Continuity in metric spaces

We have previously considered continuous functions $f : \mathbb{R} \to \mathbb{R}$. What does it mean for a function to map one metric space to another *continuously*?

Definition (Continuous function)

Suppose (\mathcal{M}, d) and (\mathcal{N}, ρ) are metric spaces, $f : \mathcal{M} \to \mathcal{N}$, and $x \in \mathcal{M}$. The function f is *continuous* at x if:

$$\forall \varepsilon > 0, \ \exists \delta > 0 \ + \ \left(y \in \mathcal{M} \ \land \ d(x, y) < \delta \right) \implies \rho \big(f(x), f(y) \big) < \varepsilon.$$

If f is continuous at every $x \in \mathcal{M}$, we say that f is *continuous on* \mathcal{M} .

- Continuity is determined point-by-point, but it is not enough to know f at a point; we must know how f behaves in a <u>neighborhood</u> of the point.
- While (\mathcal{M}, d) and (\mathcal{N}, ρ) can be any metric spaces, the most common situations are $(\mathcal{N}, \rho) = (\mathbb{R}, \text{standard})$ (so $f : \mathcal{M} \to \mathbb{R}$) and $(\mathcal{M}, d) = (\mathcal{N}, \rho)$ (so $f : \mathcal{M} \to \mathcal{M}$).
- If \mathcal{M} is a function space (e.g., C[a, b]) then $f : \mathcal{M} \to \mathbb{R}$ is often called a *functional* and $f : \mathcal{M} \to \mathcal{M}$ is often called an *operator*.

Continuity in metric spaces

It is usually helpful to rephrase the definition of continuity more geometrically in terms of balls. If we write the ball of radius δ in the distance d on \mathcal{M} as

$$B^d_\delta(x) = \{y \in \mathcal{M} : d(x, y) < \delta\},\$$

then

$$y \in \mathcal{M} \land d(x, y) < \delta \quad \iff \quad y \in B^d_{\delta}(x).$$

To rephrase the second part of the definition, for any subset $E \subseteq \mathcal{M}$, we write the *image* of *E* by *f* as

$$f(E) = \{f(x) : x \in E\} \subseteq \mathcal{N}.$$

Then, we can write " $f(x) \in B$, $\forall x \in A$ " as " $f(A) \subseteq B$ ", so the definition of continuity can be expressed concisely as

$$\forall \varepsilon > 0, \ \exists \delta > 0 \ + \ f\left(B^d_{\delta}(x)\right) \subseteq B^{\rho}_{\varepsilon}(f(x)).$$

So a function is continuous at $x \in \mathcal{M}$ if any ball about $f(x) \in \mathcal{N}$ is the image of a ball about $x \in \mathcal{M}$.

Continuity in metric spaces

As in \mathbb{R} , in a general metric space we can express continuity using sequences.

Theorem (Continuity via sequences)

Let (\mathcal{M}, d) and (\mathcal{N}, ρ) be metric spaces, and suppose $f : \mathcal{M} \to \mathcal{N}$. Then f is continuous at $x \in \mathcal{M}$ if and only if for any sequence $(x_n)_{n \in \mathbb{N}} \subseteq \mathcal{M}$

$$x_n \xrightarrow{n \to \infty} x \implies f(x_n) \xrightarrow{n \to \infty} f(x).$$

Thus, *f* is continuous on \mathcal{M} iff, for every <u>convergent</u> sequence (x_n) ,

$$\lim_{n\to\infty}f(x_n) = f\Big(\lim_{n\to\infty}x_n\Big).$$